

# Philae Landing Preparations

A recall of what happened with a personal

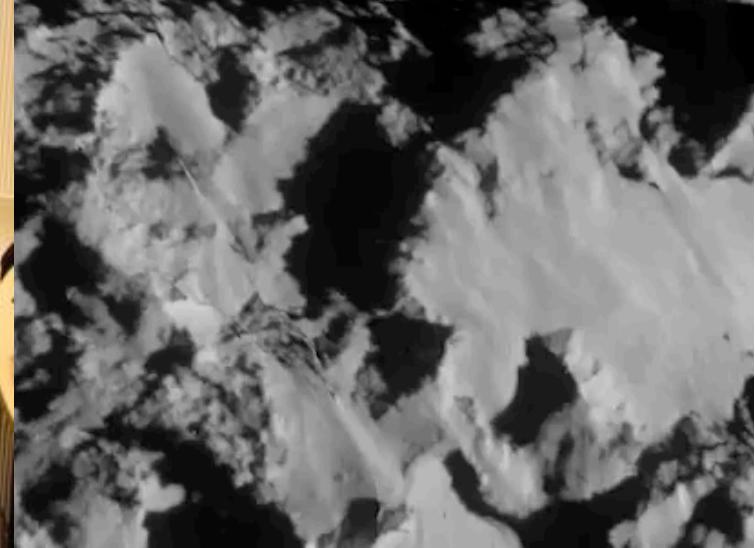
touch

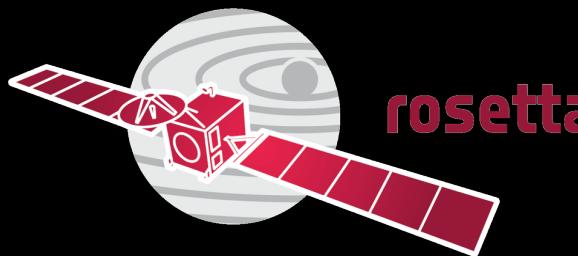
ESTEC

10 January 2018

[Joe.Zender@esa.int](mailto:Joe.Zender@esa.int)

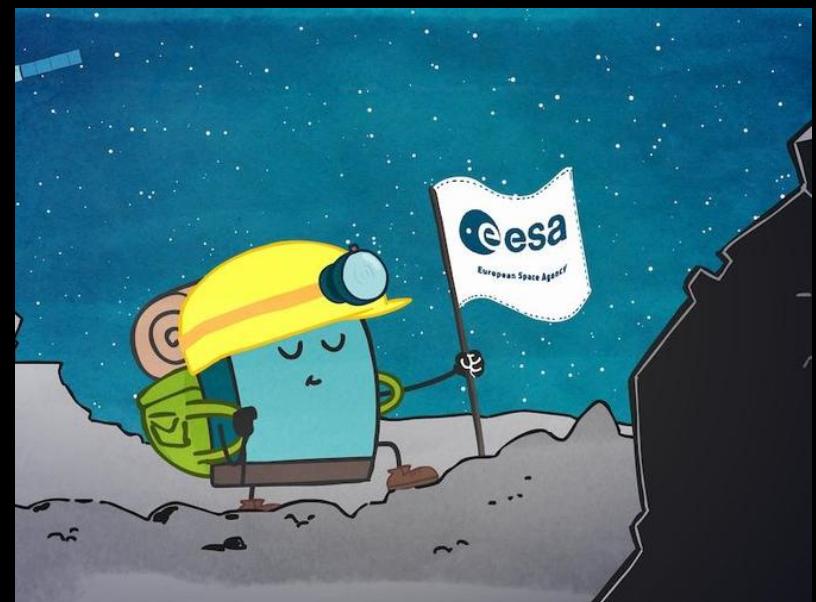
[Matt.Taylor@esa.int](mailto:Matt.Taylor@esa.int)



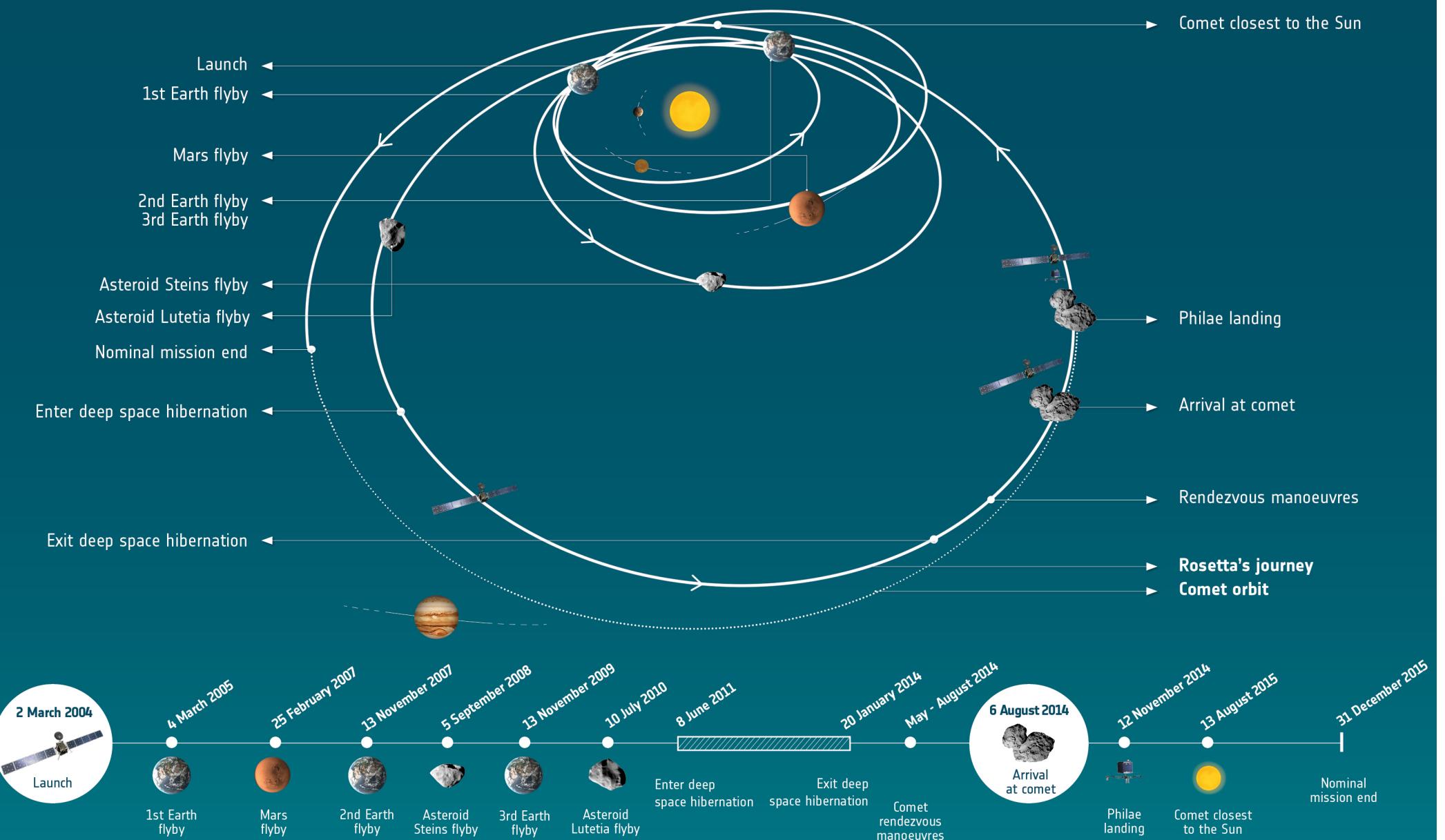


# Outline

- The year 2014: remember what we did not know
- Our Schedule: step by step



# → ROSETTA'S JOURNEY





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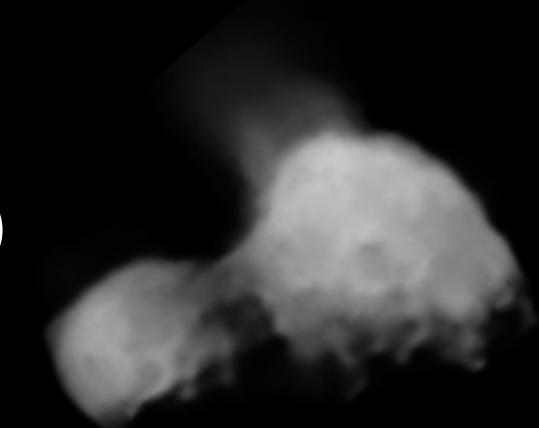
## Spacecraft Visits to Comets (imaged)

- The Halley Armada

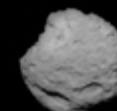
Giotto, Vega 1 and 2, Suisei,  
Sakigake

- Deep Space 1 (Borrelly)
- Stardust (Wild 2)
- Deep Impact (Tempel 1)
- EPOXI (Hartley 2)

**Fly by's - 100's km  
10's km/s**



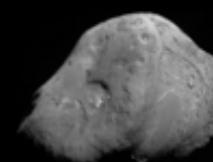
1P/Halley -  $16 \times 8 \times 8$  km



81P/Wild 2  
 $5.5 \times 4.0 \times 3.3$  km  
Stardust, 2004



19P/Borrelly  
 $8 \times 4$  km  
Deep Space 1, 2001



9P/Tempel 1  
 $7.6 \times 4.9$  km  
Deep Impact, 2005



103P/Hartley 2  
 $2.2 \times 0.5$  km  
Deep Impact, 2010



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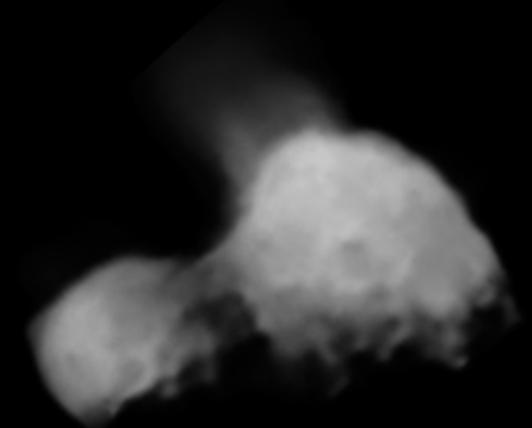
**1P/Halley:** Highly active, low albedo, relatively little geological information about the surface

**19P/Borrelly:** Diverse geology, different types of terrain, no ice found on surface!

**81P/Wild:** Rugged terrain, impact craters ?

**9P/Tempel 1:** Diverse terrain, primordial layers found?, impact craters ?, very little ice found on surface

**103P/Hartley 2:** Hyperactive, diverse terrain, extreme shape, ice blocks (cm-dm sized) emitted from nucleus



1P/Halley -  $16 \times 8 \times 8$  km



81P/Wild 2  
 $5.5 \times 4.0 \times 3.3$  km  
Stardust, 2004



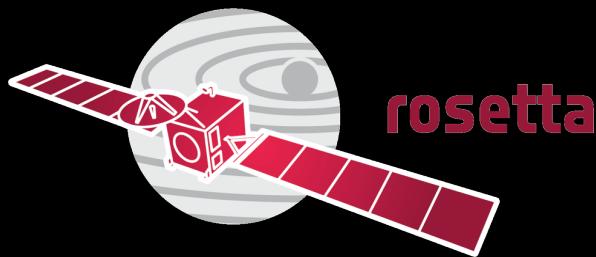
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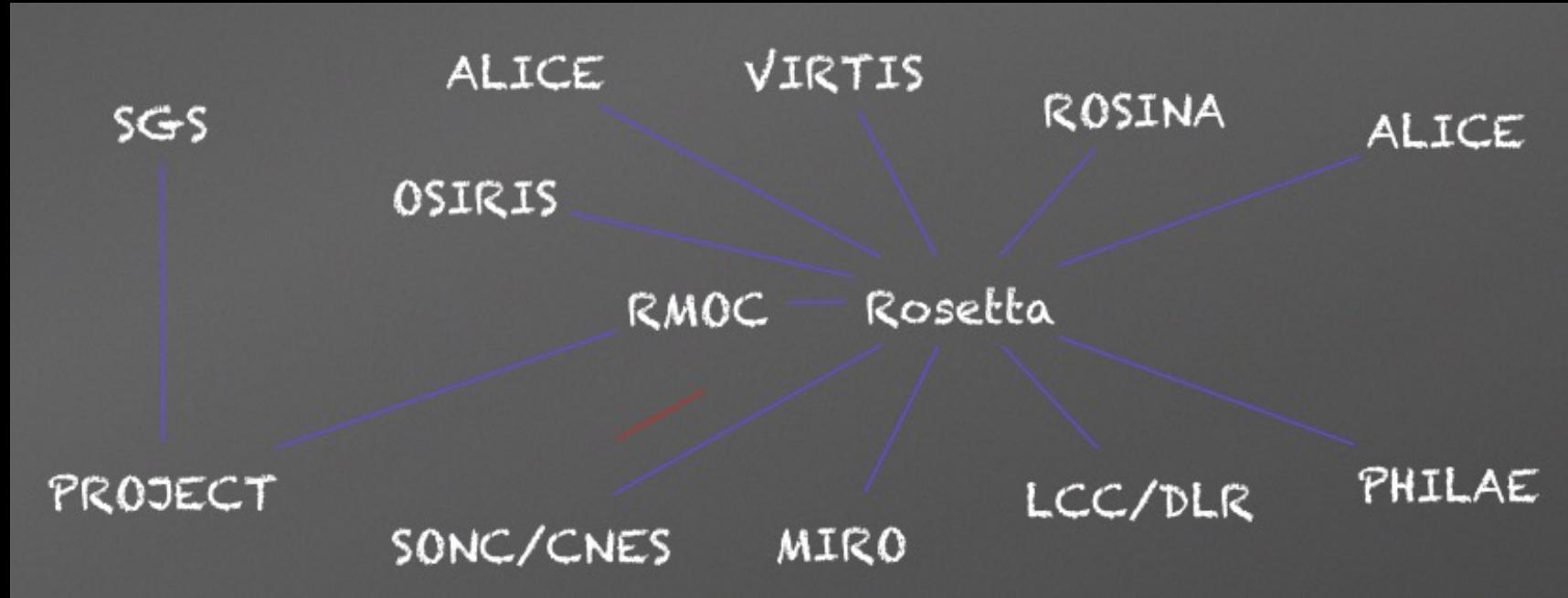
**My task:**

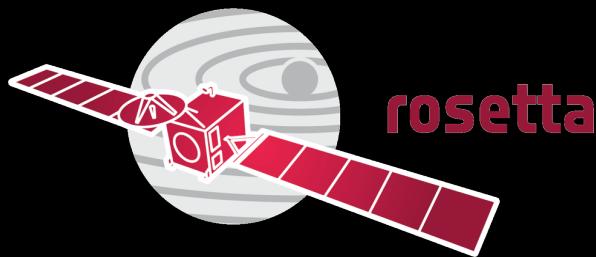
**Interface between the orbiter teams and the landing teams in all aspects of the landing site selection preparation.**

**“Identify crucial tasks and get them done.”**



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## Step-by-step



Collect information and talk to the teams:

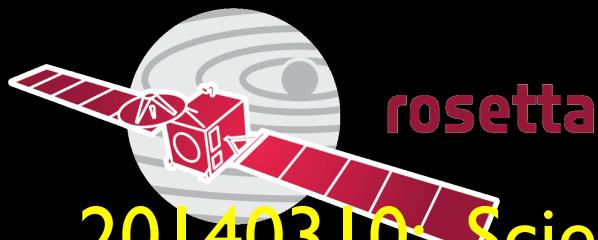
20140206: telecon with OSIRIS camera team

20140207: telecon with ROSINA ion/neutral spectrometer team

20140207: telecon with VIRTIS UV-spectrometer team

20140214: telecon with MIRO IR-spectrometer team

20140218: telecon with ALICE UV-spectrometer team



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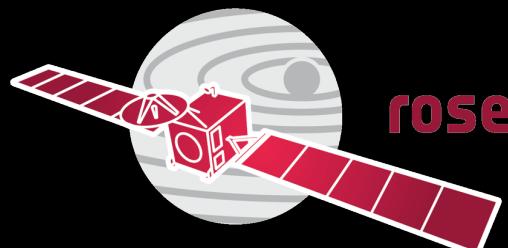
Step-by-step



## 20140310: Science Working Team meeting

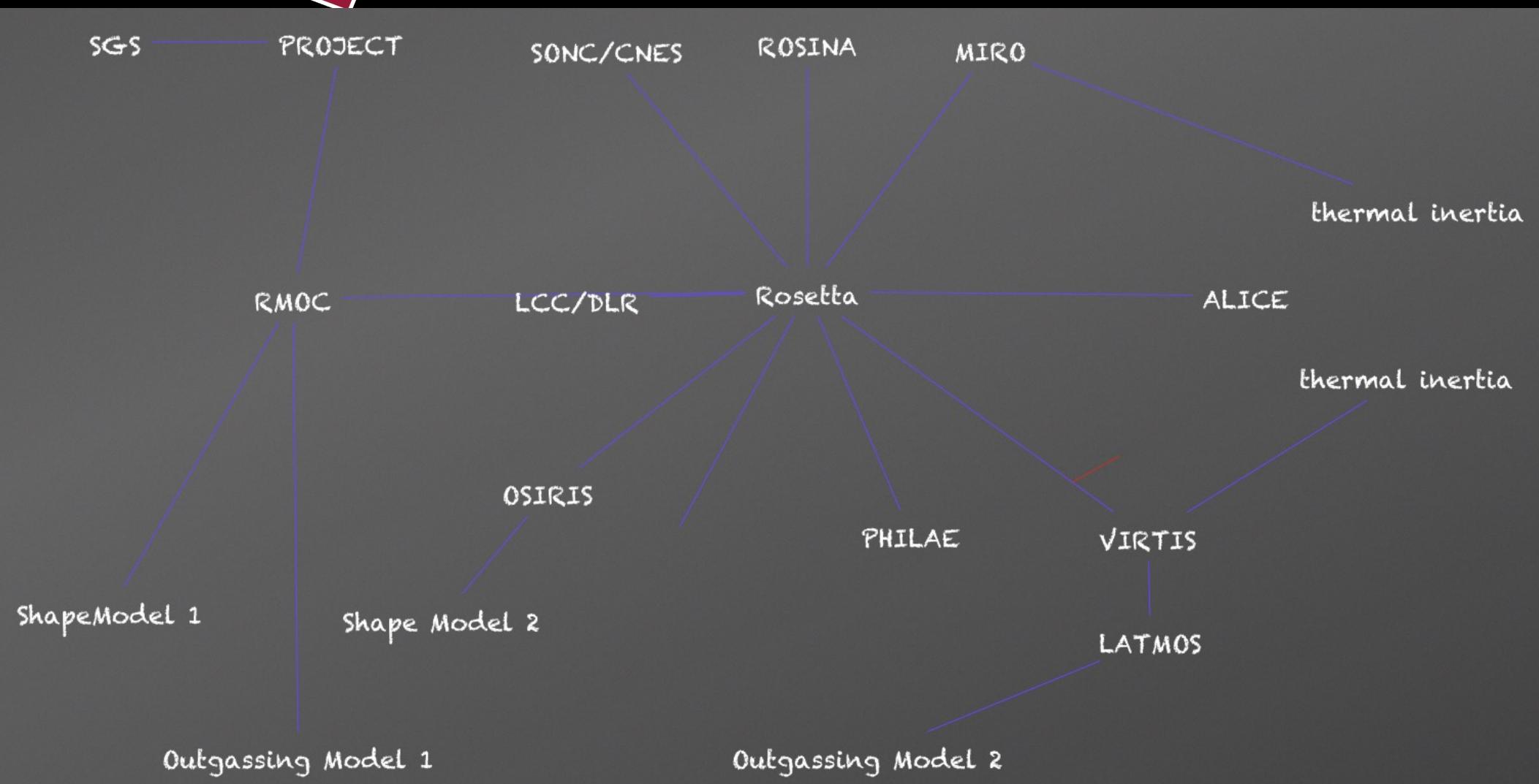
- 2 outgassing models (RMOC, LATMOS)
- who will produce the thermal model? 2 candidates: MIRO or VIRTIS?
- MIRO indicates that they miss the comet dark side shape information: it is not clear what the impact not the thermal model is.
- MIRO asks, if the SONC needs the surface gas velocity or the surface gas velocity profile? Action item for SONC.

Date/Time	Room	Topic	Participants
Monday, 14:30	H168	RLLS Validation Test discussion	SONC RLGS SGS
Monday, 16:00	H168	RLLS Validation Test: test input data and	OSIRIS RLGS MOC SONC
TBC		OSIRIS derived SPICE kernels: needs and definition	BG,MAH
Monday 18:00	H168	Comet Surface Temperature Model (CSTM): input, model, responsibility	MIRO VIRTIS SONC RLGS
Wednesday 16:00 (TBC)		LATMOS interfaces	LATMOS SONC RLGS VIRTIS
Wednesday, 14:00		Coordinate Reference Frames	SGS MOC OSIRIS



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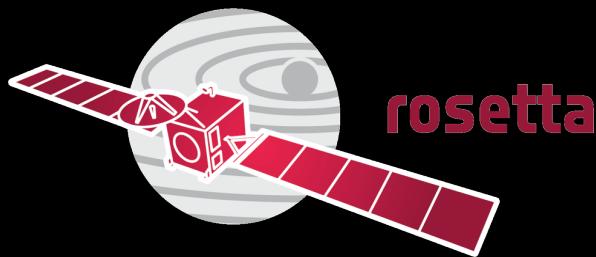
Description	Action	Due Date
<p><u>Model properties</u></p> <p>It was clarified that the RMOC model always solves for full (complex) rotation parameters. If the rotation is simple, this may be reflected in the parameters, but those parameters are not explicitly calculated.</p> <p>The origin of the coordinate system of the RMOC model is the centre of mass of the comet. The coordinate system may change slightly when the quality of the model is increased with increasing image resolution, but it will not be change arbitrarily when the model is updated.</p> <p>Flight dynamics pointed out that landmark positions are provided regularly both as Cartesian body-fixed coordinates and as pixel positions in images.</p> <p>The OSIRIS model will try to solve for simple rotation first and go for complex rotation if the residuals for simple rotation are larger than the error bars. In the OSIRIS shape model, the centre of the reference frame is the geometric centre of the shape. The difference between the centres in the two reference frames is expected to be insignificant (to be tested by OSIRIS).</p> <p>The OSIRIS model will use the rotation parameters from the RMOC model as a starting point for reconstruction. Those parameters may be (slightly) modified in the optimization process.</p>		
<p><u>Frame transformation between RMOC model and OSIRIS model:</u></p>		



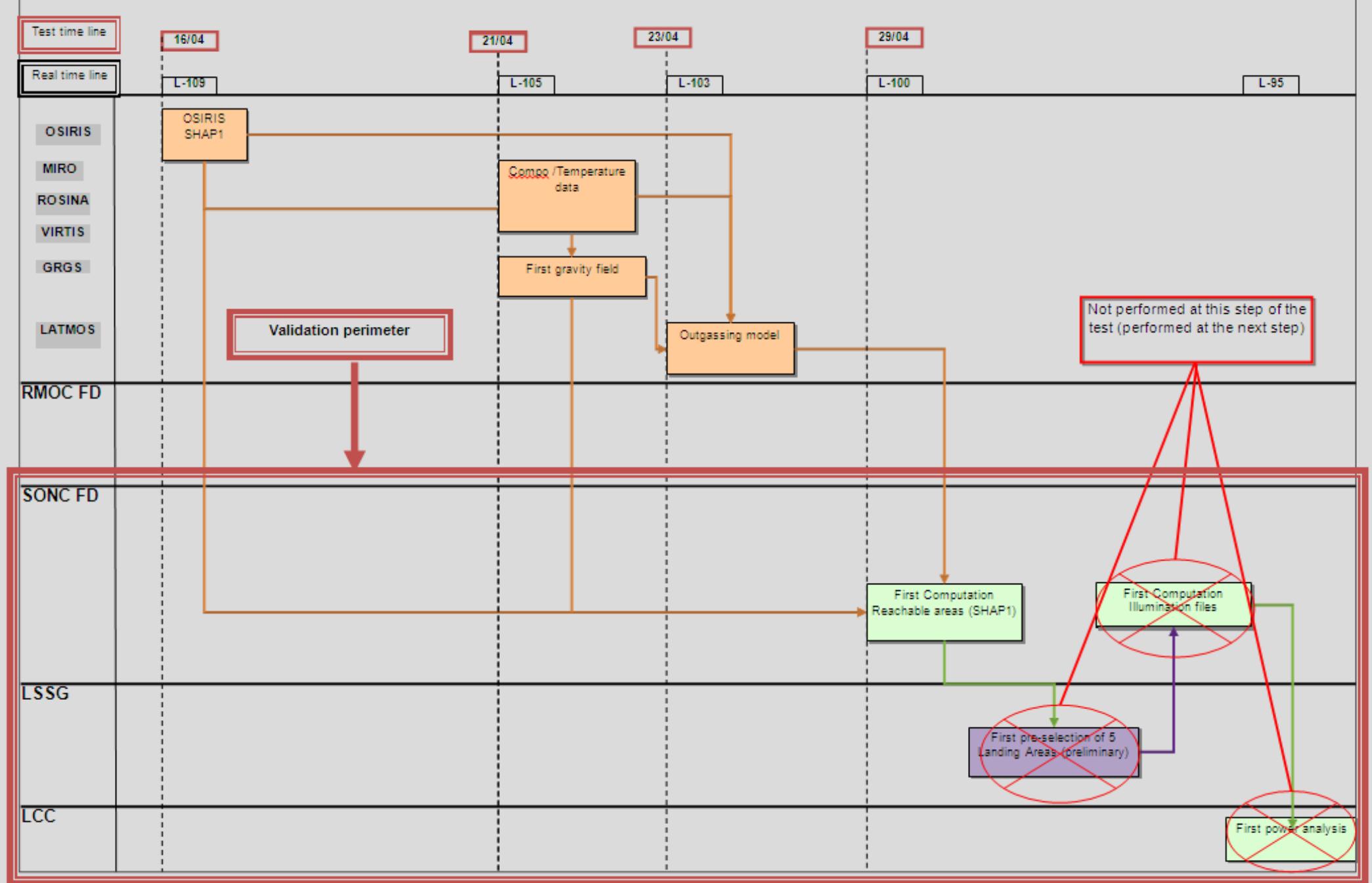
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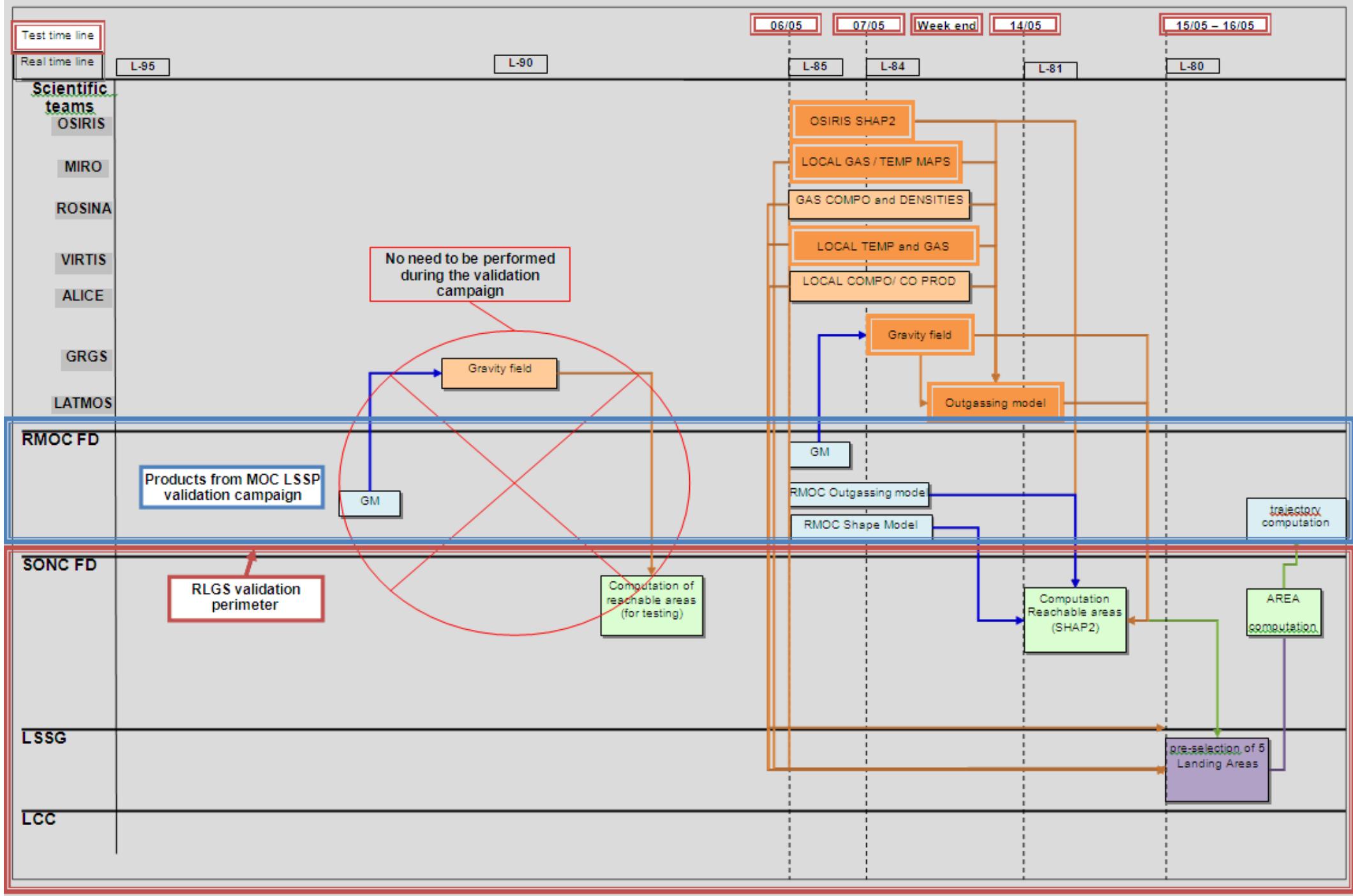
Rosetta Camera NAVCAM1 20140608

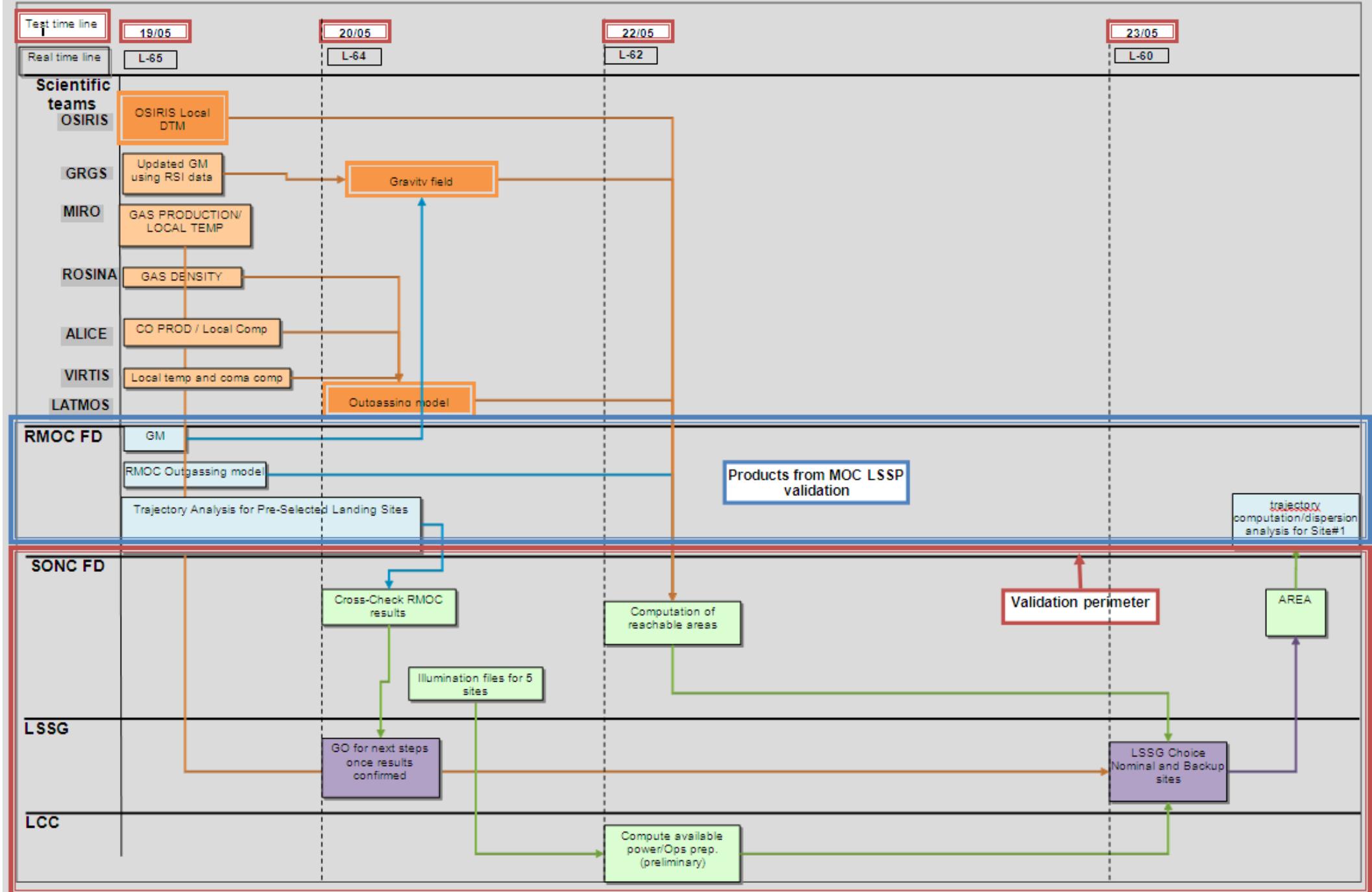


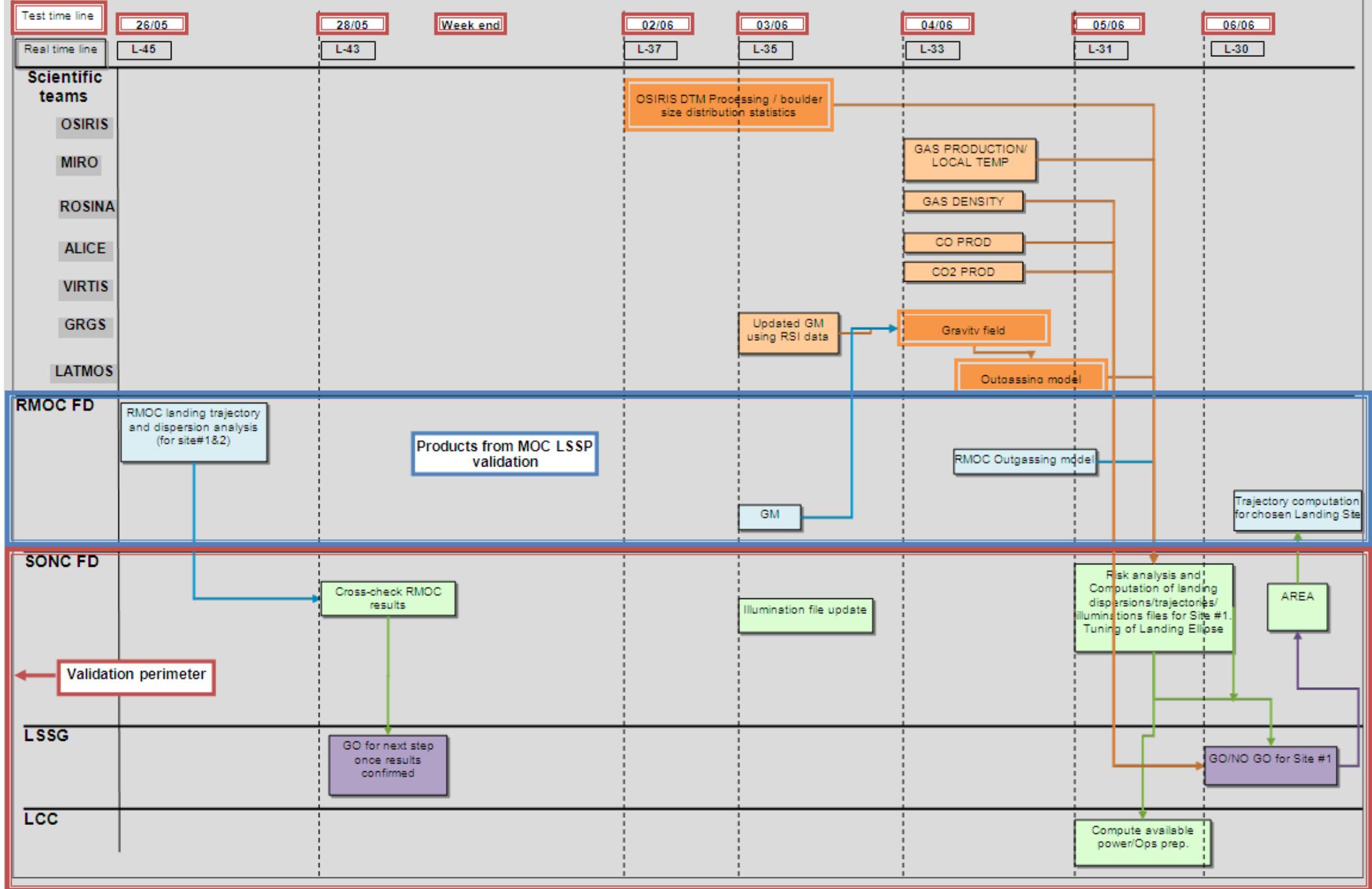


**The Plan .... the Test Plan first ... as seen by SONC in  
March 2014**









# Road Map



- Clarification about the usable inputs (RMOC & PI products) => from now to end of March
  - ▶ Usable products have to be prepared as soon as possible in order to ensure their availability for other providers who need them, and to ensure their delivery when expected for the test,
- Finalization of LSSP test with RMOC => end of March
- Test plan update/finalization => end of March
- “Warm up” test (if possible) => during April
- Test Readiness Review => end April
- LSSP phase 1 validation => 06/05 to 16/05
- LSSP phase 2 validation => 19/05 to 23/05
- LSSP phase 3 validation => 26/05 to 06/06
- Post Test Review => mid June
- ESA LSSP Readiness Meeting => 01/07

Products (wrt ICDs)	Classification	Producer	Product available for test?
Shape model "RS_GLOBAL_DTM_500m", "RS_GLOBAL_DTM_20m"	SHAP1 important; SHAP2 & SHAP2MIRO <b>Mandatory</b>	OSIRIS	
rotational parameters/model "RS_ROT_PARAM_500m", "RS_ROT_PARAM_20m", "RS_ROT_PARAM_LOCAL_DTM", "RS_ROT_PARAM_IMAGES_LS"	<b>Mandatory</b>	OSIRIS	
Local DTM (3m resolution) "RS_LOCAL_DTM"	<b>Mandatory</b>	OSIRIS	
Images high resolution "RS_IMAGES_LAND_SITE1", , "RS_IMAGES_LAND_SITE2", ,	<b>Mandatory</b>	OSIRIS	
obstacle size distribution "RS_BOULDERS_LAND_SITE1, RS_BOULDERS_LAND_SITE2"	<b>Mandatory</b>	OSIRIS	
Colormaps, composition "RS_GLOBAL_COMPOSITION", "RS_LOCAL_COMPOSITION"	Important	OSIRIS	
Albedo map "RS_ALBEDO_500m" "RS_ALBEDO_20m"	Valuable	OSIRIS	
Dust and gas coma monitoring "RS_MONITORING_DUST_date", "RS_MONITORING_GAS_date"	Valuable	OSIRIS	
Inner coma monitoring "RS_MONITORING_INNER_COMA_date"	Valuable	OSIRIS	
"Far global density measurements of H2O, CO and CO2", "DLR	Important	ROSINA	

Products (wrt ICDs)	Classification	Producer	Product available for test?
"Global density measurements of H2O, CO and CO2"	Important	ROSINA	
"Close local measurements of H2O, CO and CO2"	Important	ROSINA	
"Global measurements of total gas density"	Important	ROSINA	
"Close local measurements of total gas density"	Important	ROSINA	
"Total density and gas dynamics measurements"	Important	ROSINA	
"Global Surface compos"	Important	ALICE	
"Surface of Candidate Landing Sites"	Important	ALICE	
"Global CO Gas Production"	Important	ALICE	
"CO Gas Production at Candidate Landing Sites "	Important	ALICE	
"Surface composition"	Important	VIRTIS	
"Surface temperature predictions and thermal properties" (TI)	<b>Mandatory</b>	VIRTIS & MIRO	
"Coma composition"	Important	VIRTIS	
"Global H2O and CO gas production rates	<b>Mandatory</b>	MIRO	
"Local gas production and variability"	Important	MIRO	
« Temperature predictions of nucleus » (TI)	<b>Mandatory</b>	MIRO & VIRTIS	
"Temperature map of candidate landing sites	Important	MIRO	
"Gas production, velocity, and variability of candidate landing sites"	Important	MIRO	
"Antenna temperatures during selected night-time limb crossings"	Important	MIRO → Osiris	

from Jens Biele, LCC, March 2014



# Landing Site Selection: Status of essential Orbiter Instrument Products

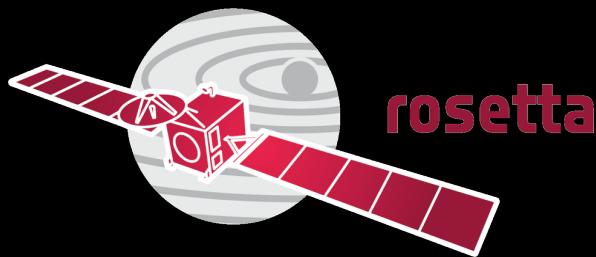


Product	Originator	Data Pipeline	Interface validation	E2E test preparation
20m Products	OSIRIS	in validation	Executed, awaiting confirmation, delta tests necessary	In preparation
3m Products	OSIRIS	In validation	Executed (ac)	In preparation
High-resolution images	OSIRIS	validated	Executed (ac)	Ready for test
List of boulders	OSIRIS	validated	Executed (ac)	Ready for test
Comet Surface Temp Model	VIRTIS/MIRO	In development	In preparation	In preparation
Gravity model	GRGS/CNES	No information	No information	No information
Outgassing model	LATMOS/CNES	No information	No information	No information

# Landing Site Selection: Status of important Orbiter Instrument Products (not part of E2E test in May 2014)



<b>Product</b>	<b>Originator</b>	<b>Data Pipeline</b>	<b>Interface validation</b>
H20, CO and CO2 measurements	ROSINA	Validated	executed successfully
Gas density	ROSINA	Validated	Executed successfully
Surface composition (global/local)	ALICE	Validated	Ready for testing
CO gas production (global/local)	ALICE	Validated	Ready for testing
COMA composition	VIRTIS	validated	Executed successfully
Surface composition	VIRTIS	validated	Executed successfully
H20, CO gas production	MIRO	In development	Executed successfully
Temperature maps (global/local)	MIRO	In development	Executed successfully
	MIRO	In development	Executed



To get all the model output, one needs  
first: to plan and acquire the data  
second: to downlink the data  
and third: to have good data and success with the  
computations.

and here is THE Plan ... as seen from Project ...

open 01-RO-SGS-LI-1014\_1\_3\_LSSP\_InputProductsOverview\_20140730



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Juni 2014

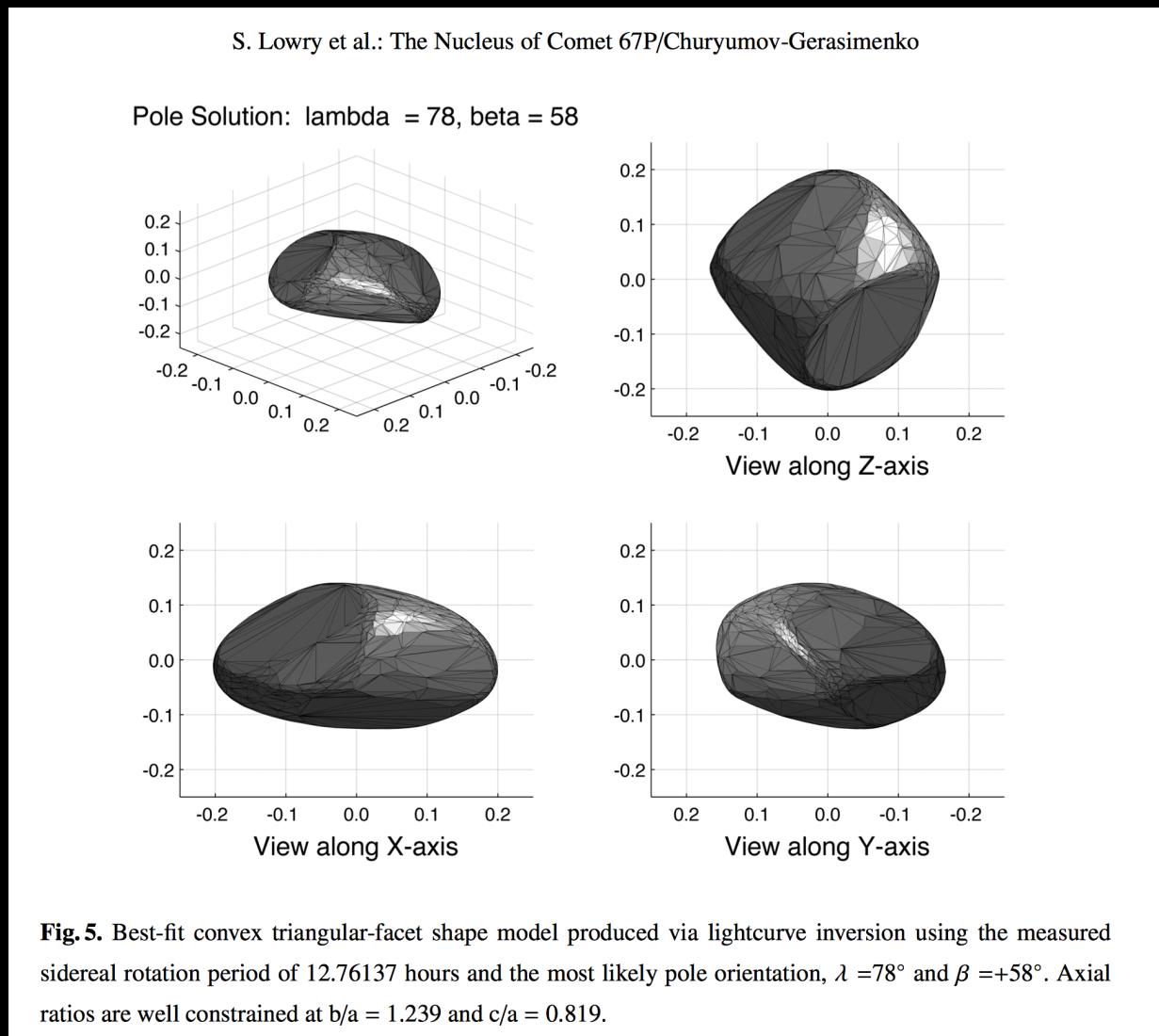


gebaseerd op

- > Optische technieken  
(lightcurves) uit telescoop  
waarnemingen
- > Thermische analyse en  
optische fotometrie
- > Spitzer thermische IR data

We verwachten (bijv. Op basis  
van Lowry et al, 2012)

- > Axiale ratio's:  $b / a = 1.239$ ,  $p / a = 0,819$  (7% marge)
- > Spin rate: 12.76 uur
- > Pol:  $\lambda = 78 (+ -10)^\circ$ ,  
 $\beta = 58 (+ -10)$  graden
- > Nucleus fase verduistering:  $G = 0,11 (+ -0,12)$ ,  $H_r = 15,31 (+ - 0,07)$
- > Thermische inertie:  $< 15 \text{ J} / \text{m}^2 / \text{K} / \text{sqrt(s)}$

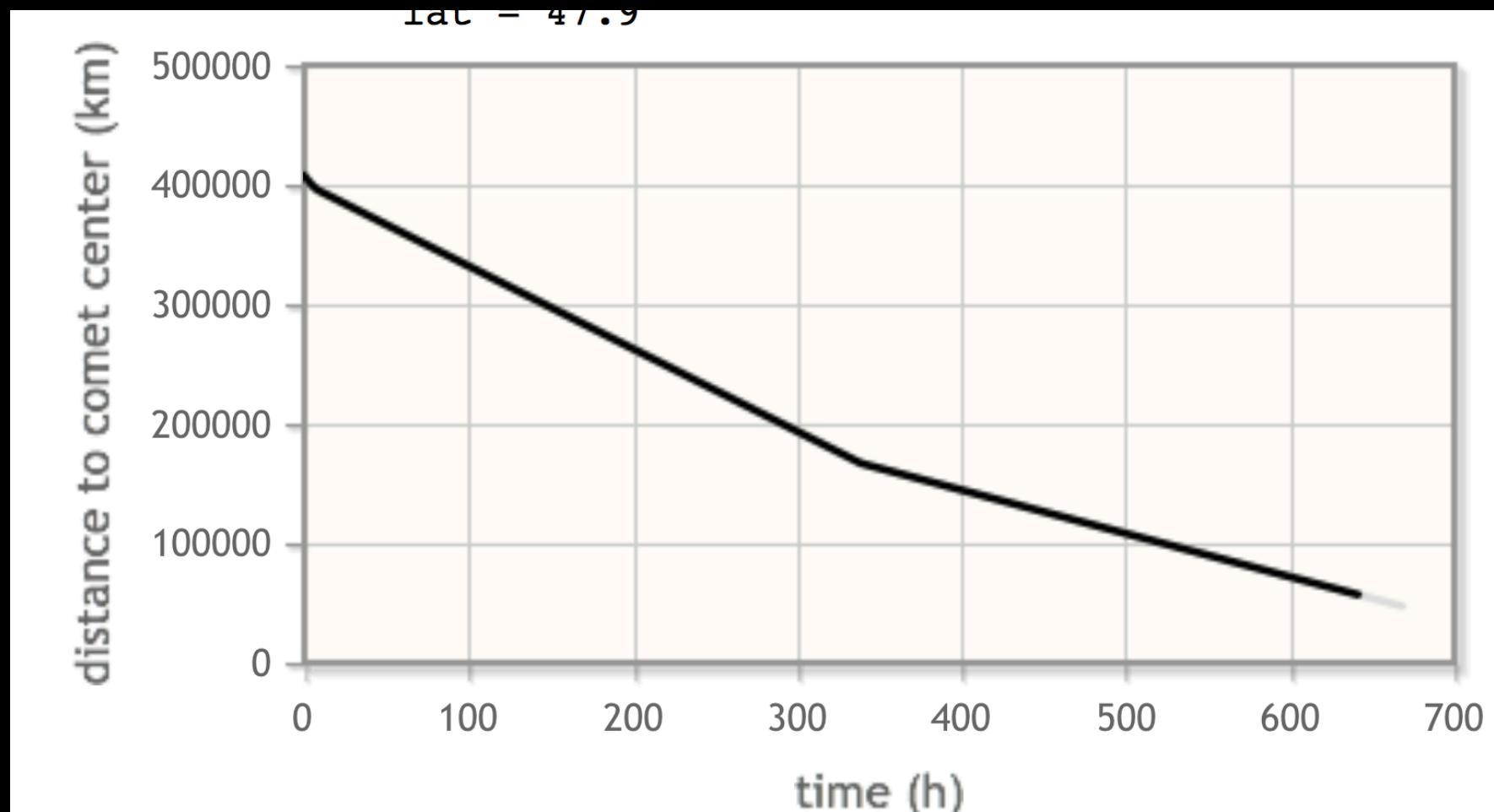




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afstand van de komet in juni 2014





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Rosetta Camera NAVCAM1 20140608

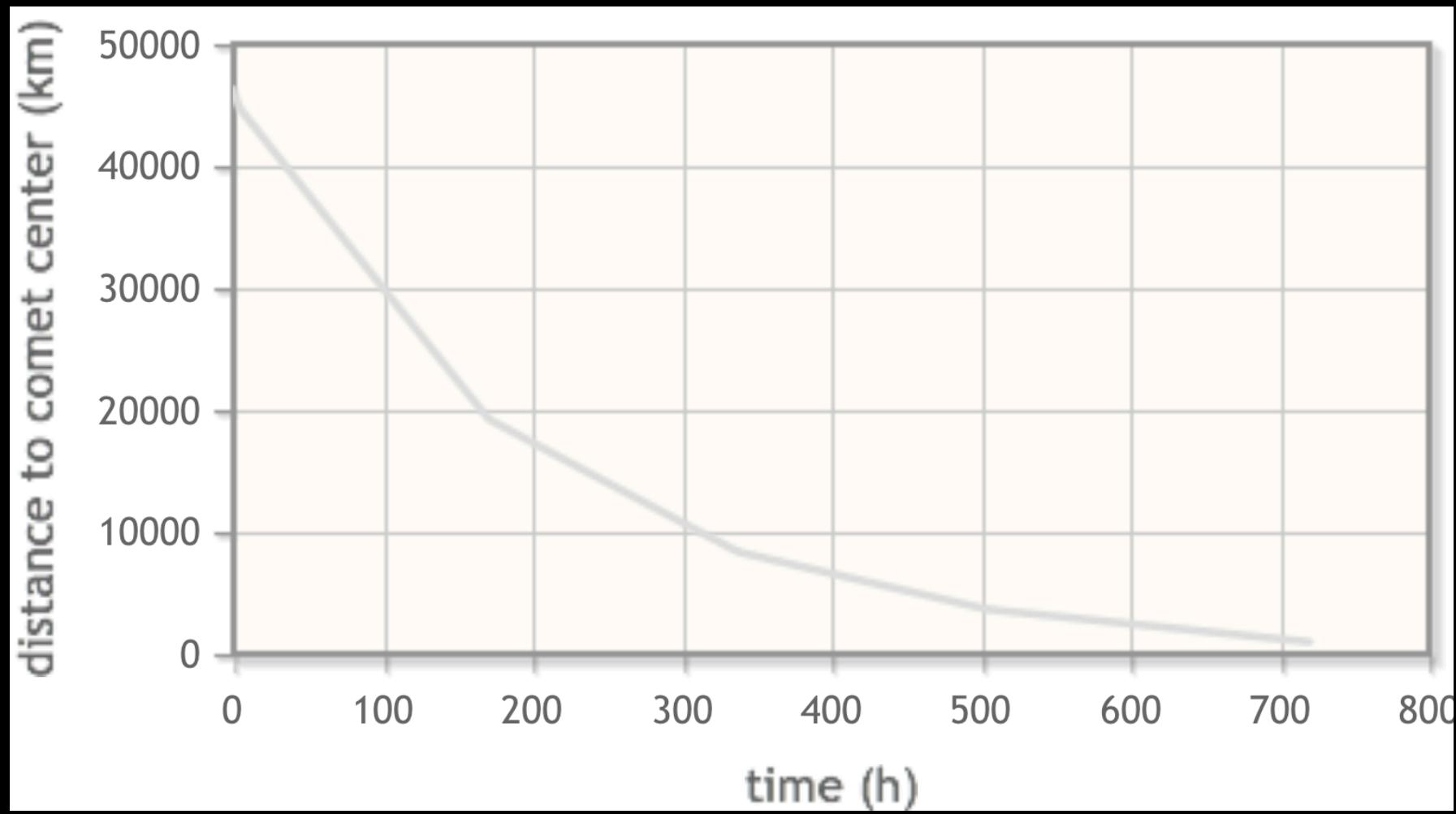


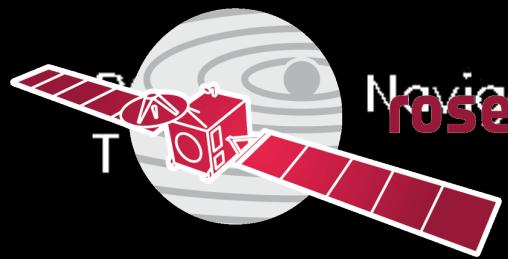


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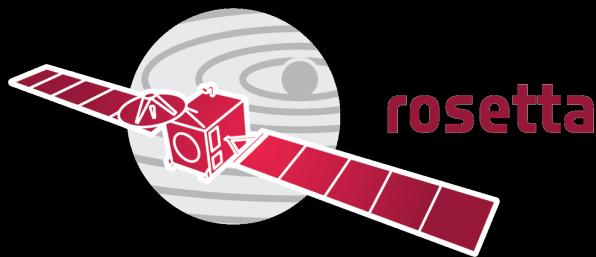
afstand van de komet in juli 2014





Navigation Camera NAVCAM1 20140703





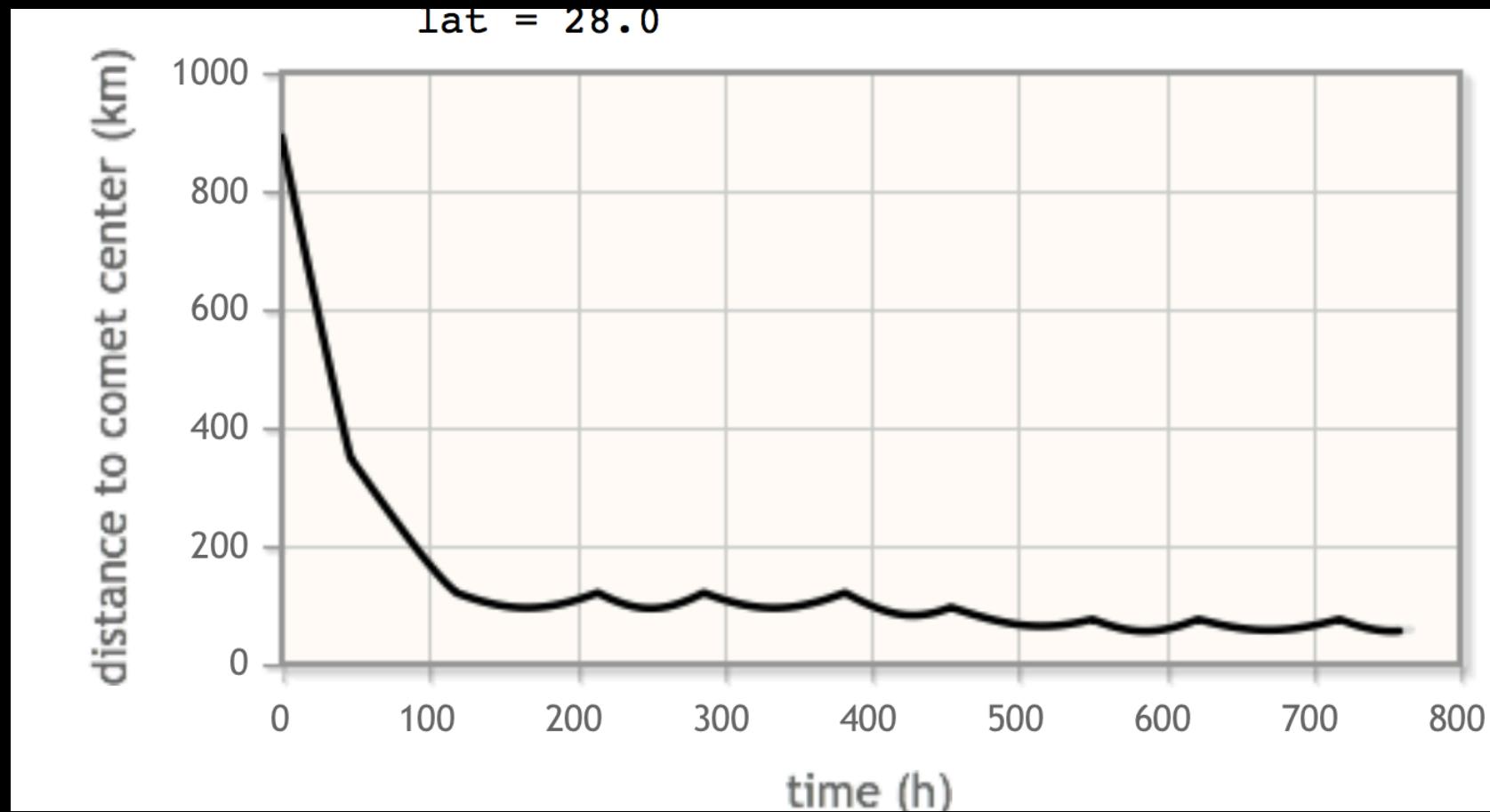
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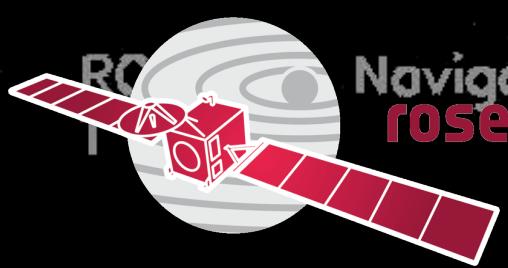
**It was clear at the end of July 2014, that parameters and models  
needed adaptations and additional validation ...**

**... but we did not yet have the full knowledge ... and decided to  
go on ...**

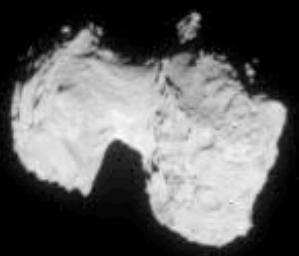


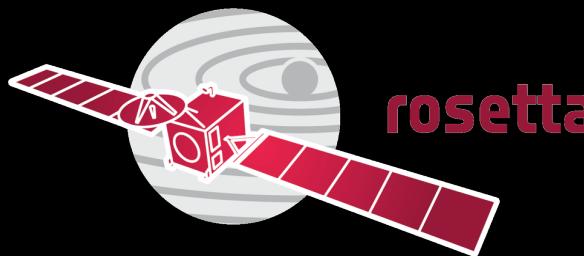
afstand van de komet in augustus 2014



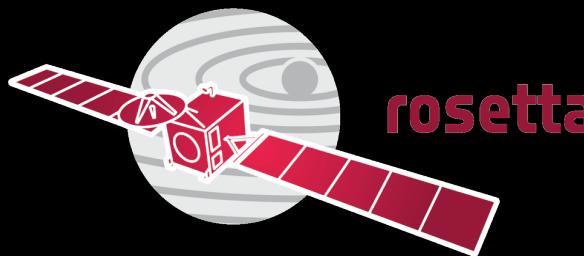


Navigation Camera NAVCAM1 20140803  
**rosetta**





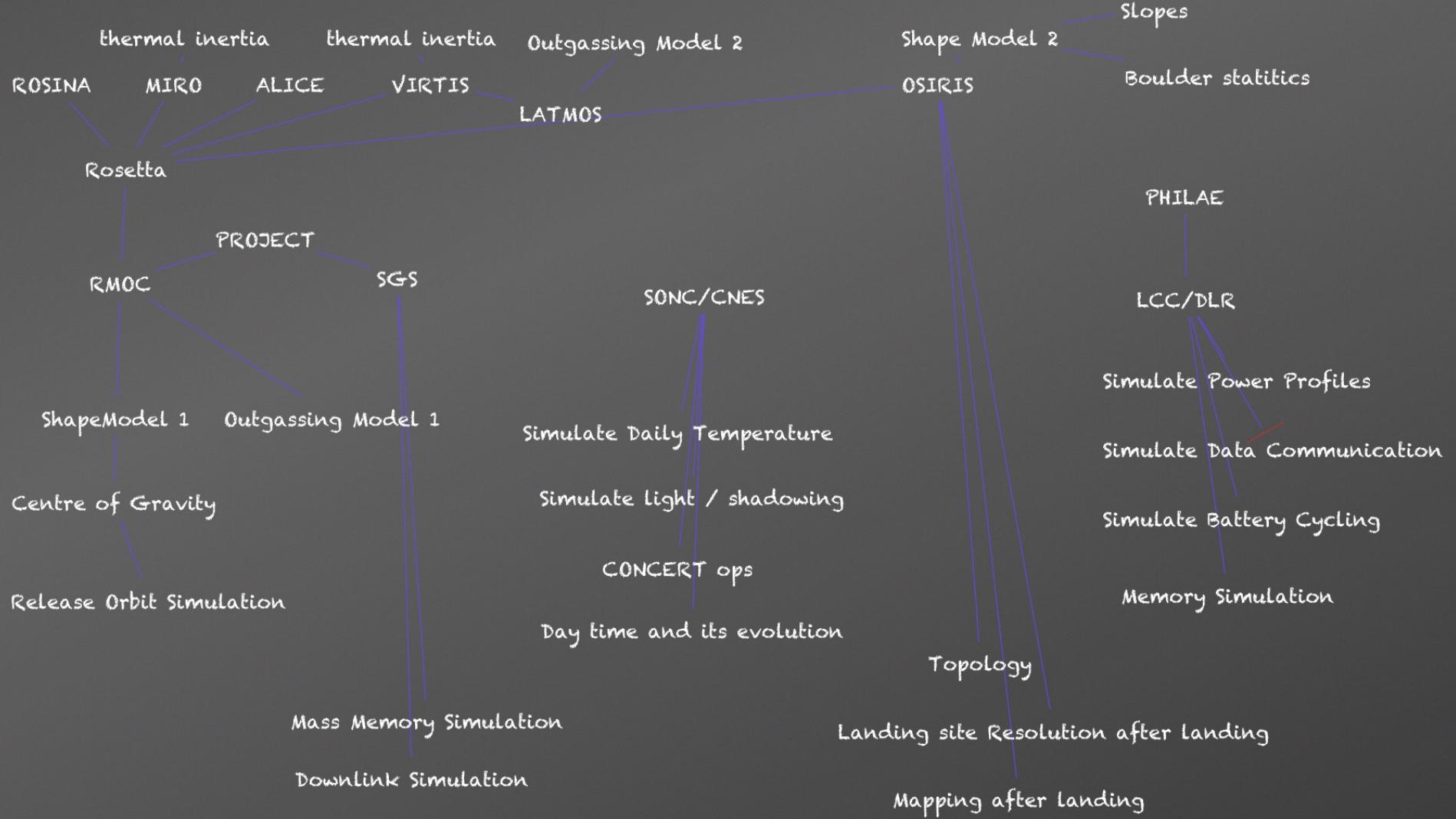
**... with limited information, we  
went into the landing site selection meeting on 4-5 August  
2014 ...**



## status eind augustus:

- > Gaida detecteert de eerste stofdeeltje (1 augustus 2014)
- > Pre-selectie van 10 landingsplaatsen (21 augustus 2014)
- > komeet massa: oorspronkelijke raming:  $3 \times 10^6$  kg, nu  $1 \times 10^6$  kg
- > Radius: oorspronkelijke raming:  $\sim 2.1$  km, nu [0.6, 2.8] km
- > Dichtheid: 3 modellen werden gebruikt: 100/370/800 kg / m<sup>3</sup>
- > Obliquity/schuinheid is constant: 53 graden -> CoG?
- > CG buiten FOV van NavCam (22 augustus 2014)  
Selectie van 5 landingsplaatsen (24 augustus 2014)
- > Comet activiteit schatting en overeenstemming over wat er draait in LTP4 te vliegen (29 augustus 2014)
- > Thermische kaart op komeet uit OSIRIS (29 augustus 2014)

Name	Site	Long. / Lat.	Illumination 11/11/14	Illumination 01/11/15	Landing Scenario	Dynamical Slope	Consent Color	Risk
LA_10	A	174 / 72	8.1	7.6	O1 – 6:30-8:3	15	Red	Medium
In_Crater_2	B	353 / 5.2	6.4	6.3	O1 – 6:30-8:3	11	Green	Low
LA_16/HBO_4/ LA_12	C	205 / 26	7.6	7.2	O1 – 4:30-6:3	20	Yellow	Medium
LA_14/HBO_3	D	134 / 45	10.3	9.1	O1 – 4:30-8:3	5	Yellow	Dispersion ellipse
LA_15/HBO_2	E	(78 / 24)	11.4	9.5	O1 – 6:30-8:3	10	Green	Low
LA_17/HBO_5	F	318 / 22	9.7	8.8	O1 – 4:30-6:3	22	Yellow?	Medium
LA_13	G	105 / 50	10.0	8.8	O1 – 6:30-8:3	20	Red	Medium
Polar_Day	H	133 / 59**	12.48	12.48	None	15	None	Low
HBO_1	I	14 / 23	9.12	8.21	O1 – 4:30-6:3	10	Green	Dispersion ellipse
SFD_1	J	335 / 25				25		



S/C security

Landing Site (as a statistical parameter)

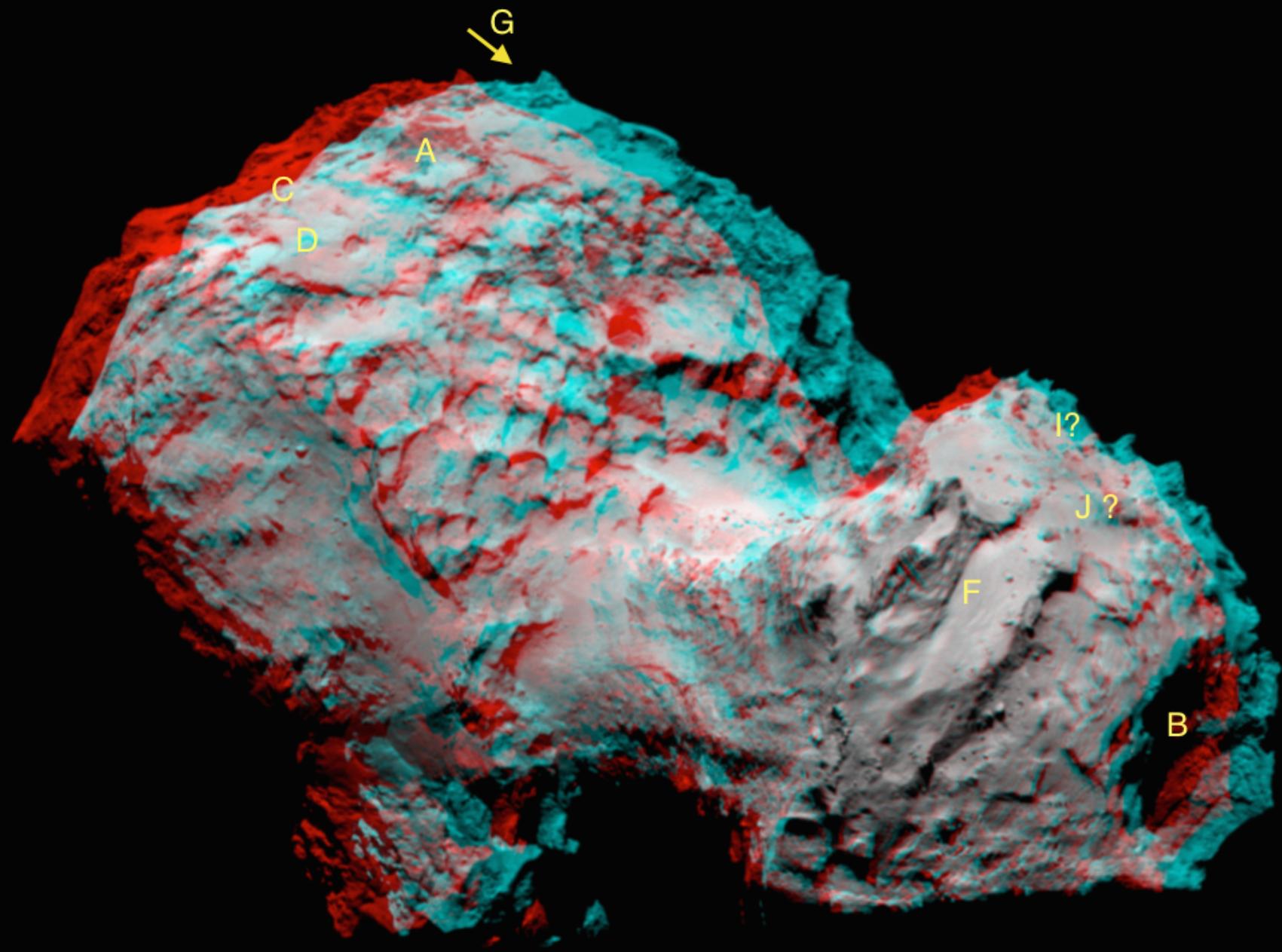
Outreach

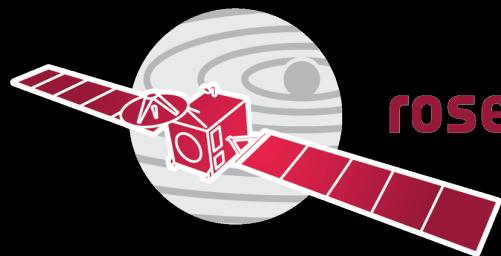
Science during Descent

First Science Sequence

Long Science Sequence

Lead Scientist

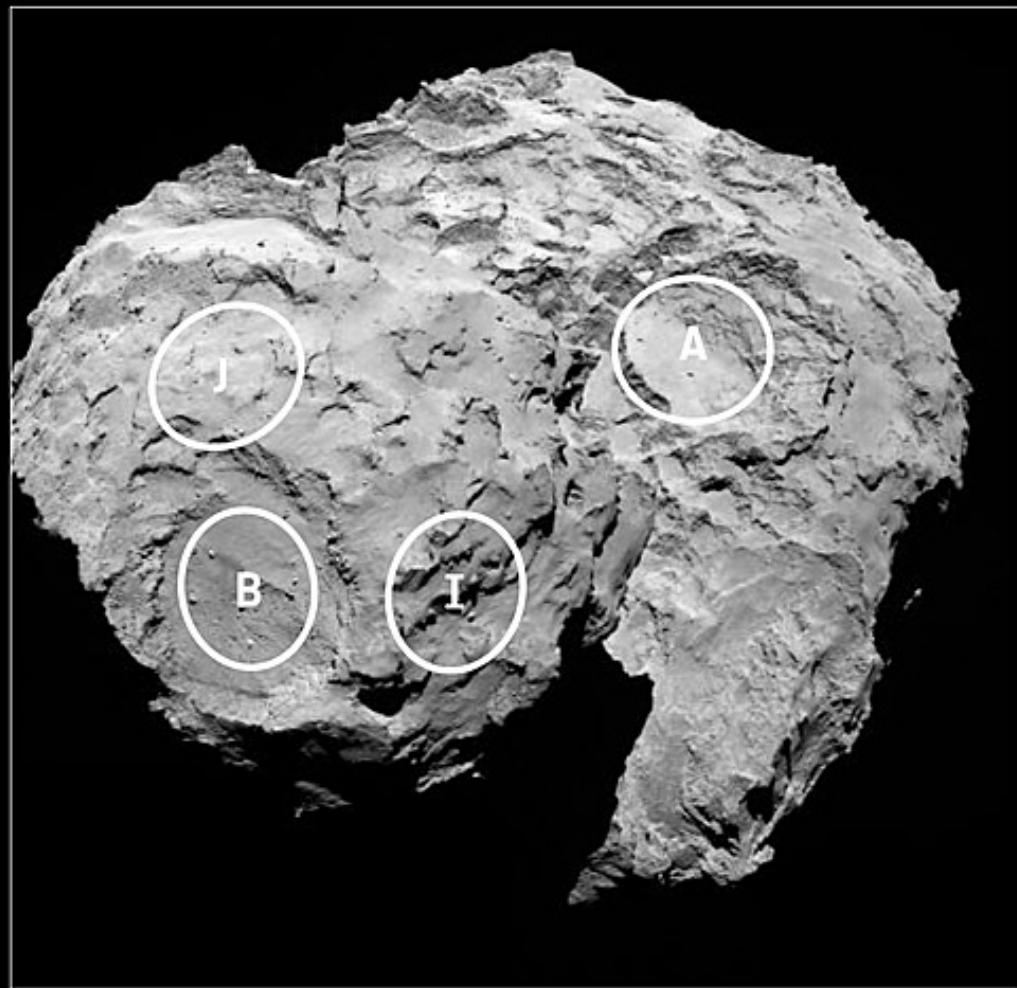


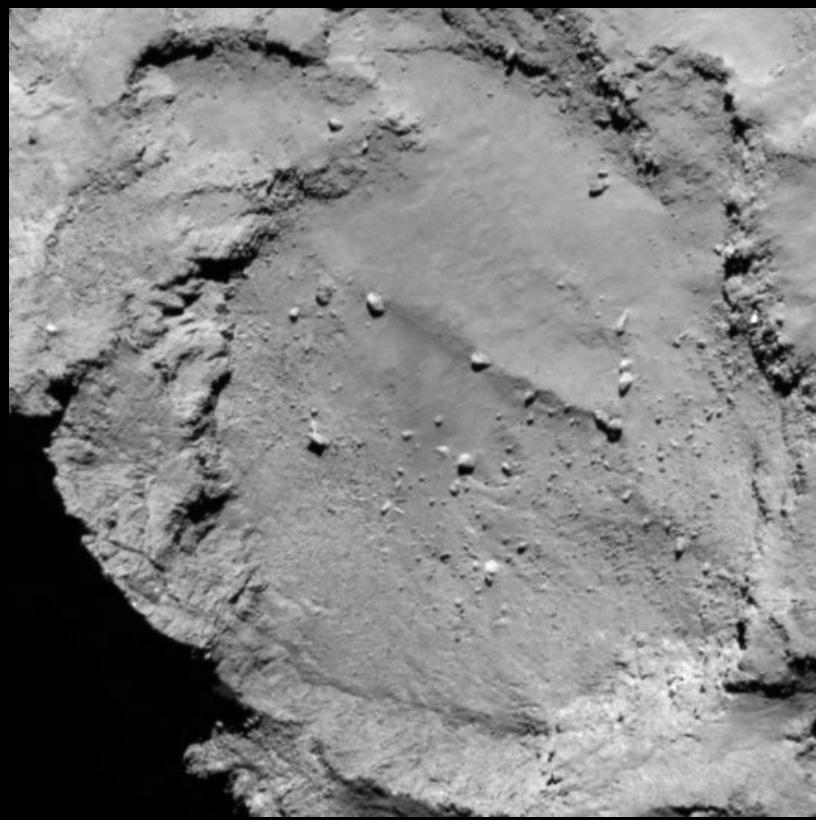
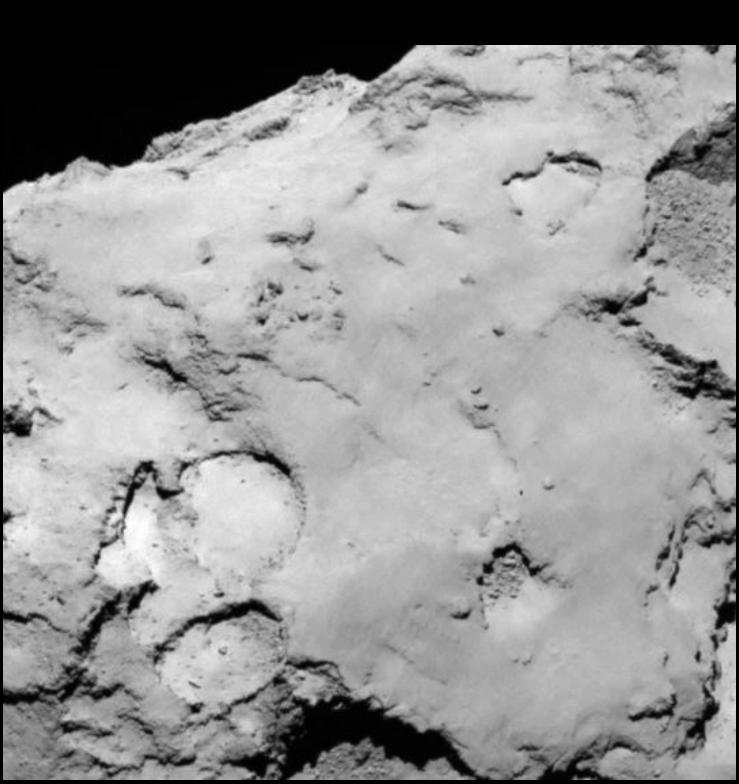
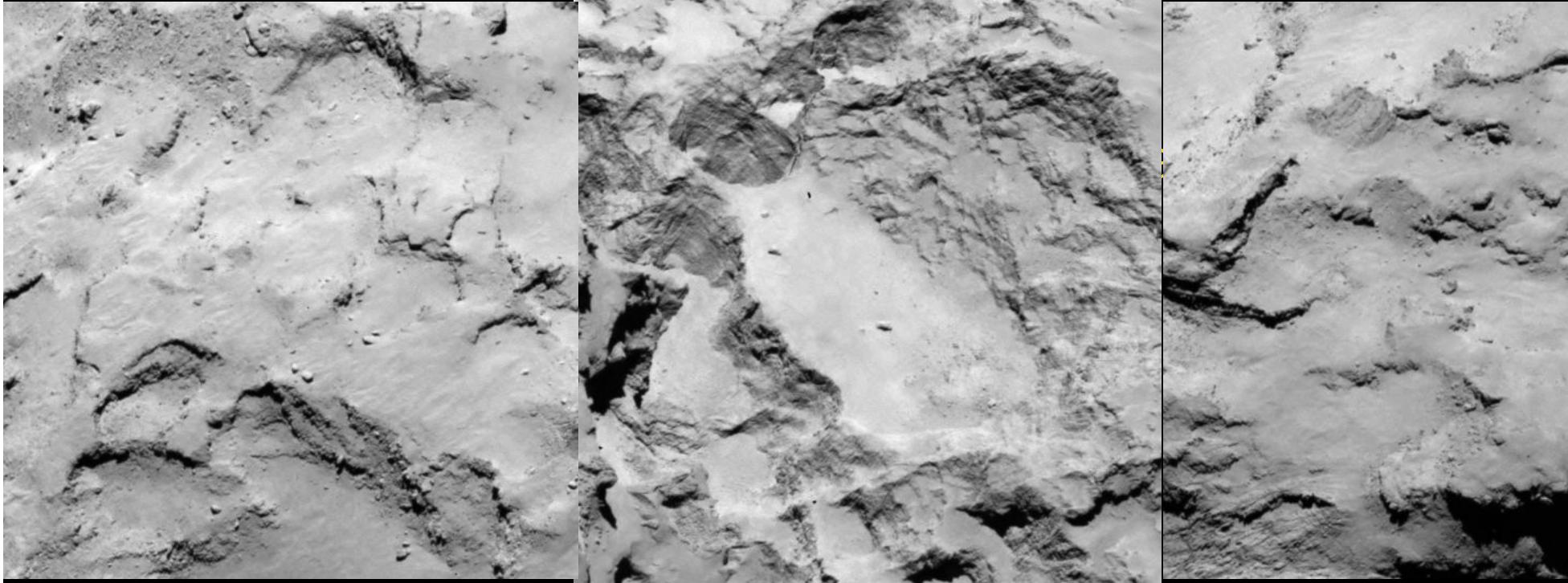


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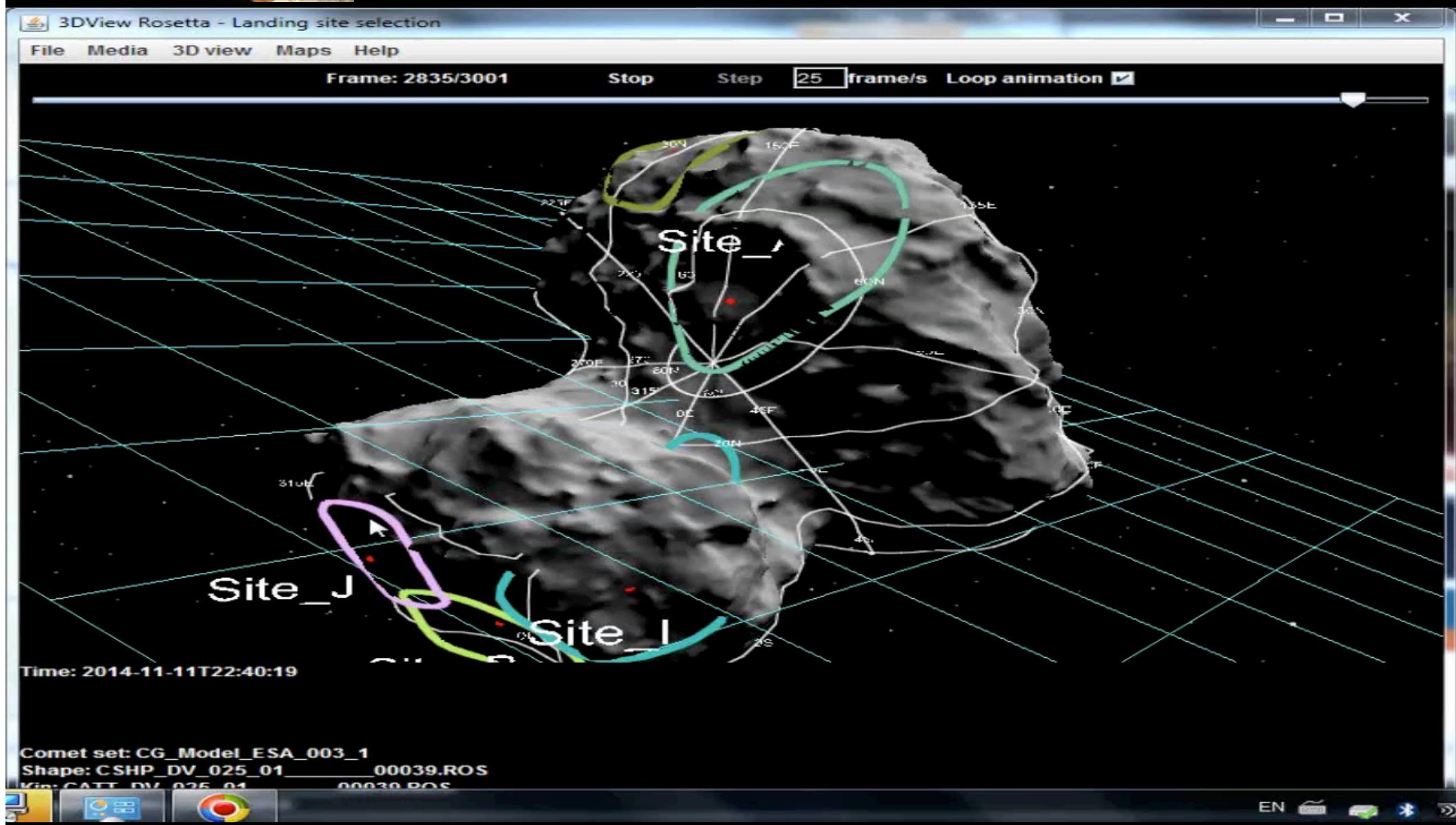


the selected landing spots from 5 August 2014





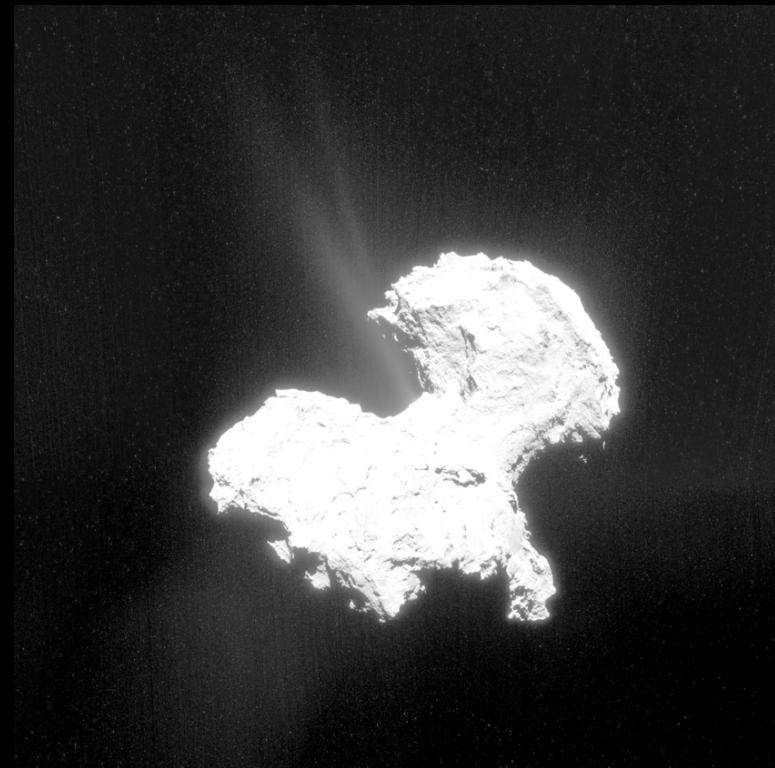
European Space Agency

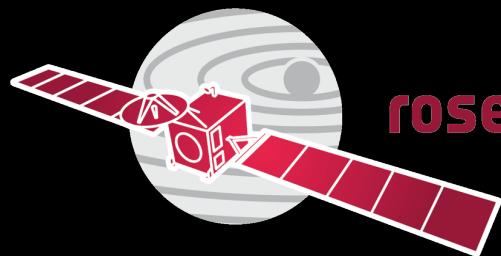




rosetta

3 september 2014





rosetta



from M. Malmer

European Space Agency



rosetta

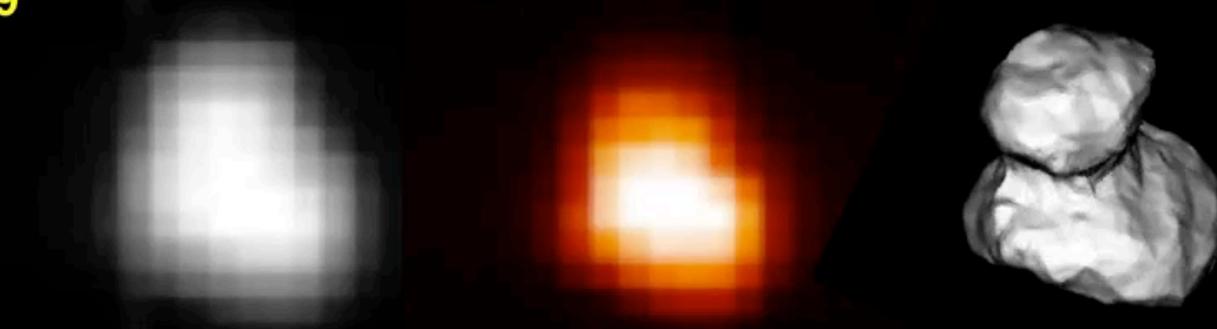


67P/CG NUCLEUS

2014-07-28T15:39

470 m/px

ESA/Rosetta/VIRTIS/INAF-IAPS/OBS DE PARIS-LESIA/DLR



VIRTIS-M

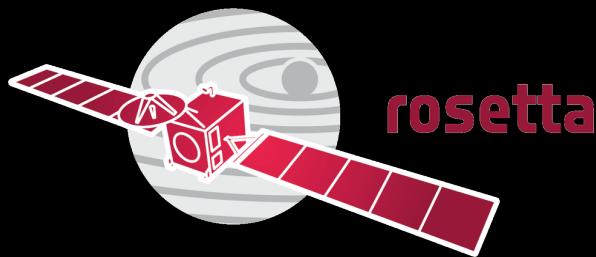
1.4  $\mu\text{m}$

5  $\mu\text{m}$

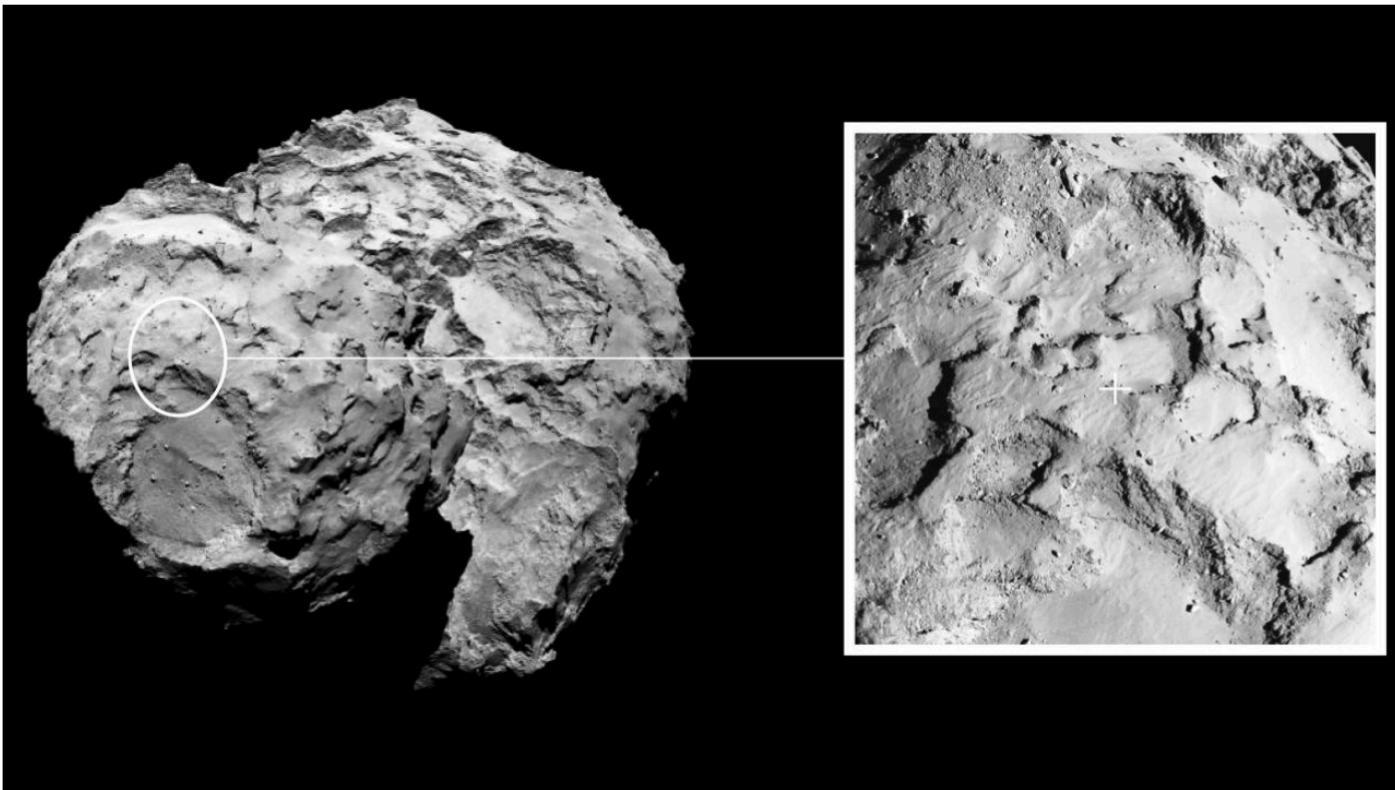
shape model rendering







Selection of prime landing site on the week-end of 13/14  
September 2014 (see ON\_LSSP2 meeting  
organization\_Draft\_270814)

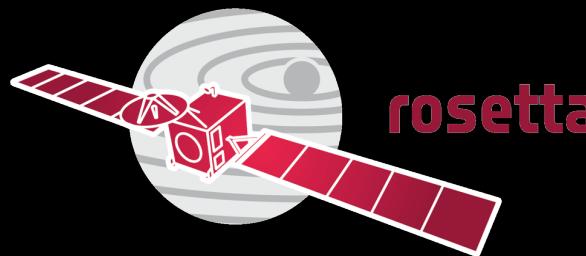
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Circle marks landing spot: Lander hopes to avoid jets of gas and dust that could complicate descent.

ESA/Rosetta/MPS for OSIRIS Team MPS/UPD/LAM/IAA/SSO/INTA/UPM/DASP/IDA

## Comet landing site picked: Rosetta to aim for the J spot

By **Eric Hand** | Sep. 15, 2014, 8:15 AM



10 November 2017: GO/NOGO



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# MEMO

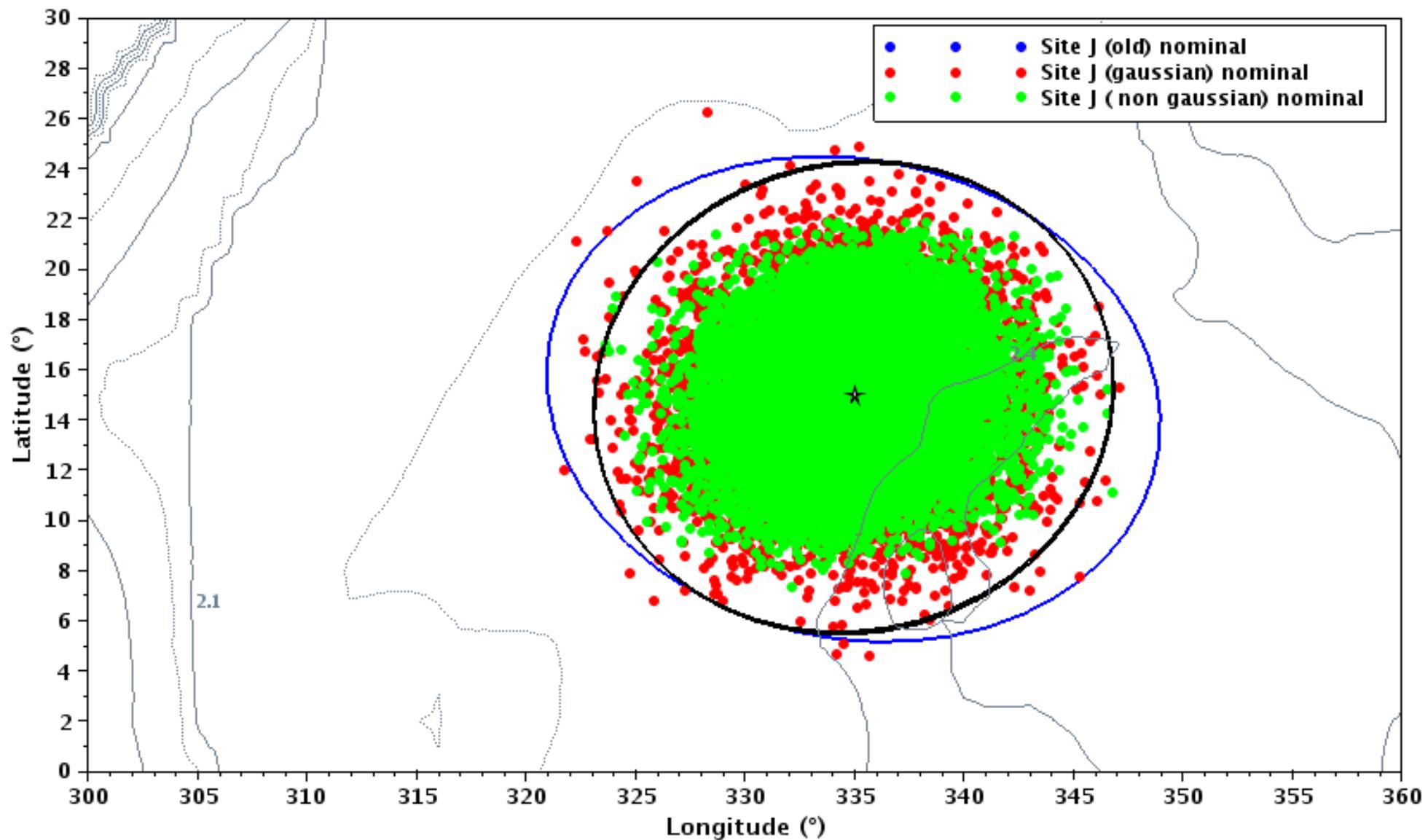
<b>Date</b>	09/10/2014	<b>Ref</b>	RO-ESC-ME-5508
<b>From</b>	C. Casas	<b>Visa</b>	
<b>To</b>	S. Ulamec, J. Biele, B. Paetz, M. Maibaum, K. Geurts, C. Fantinati, P. Gaudon, E. Jurado, C. Delmas, A. Blazquez (RLGS)	<b>Copy</b>	M. Ashman (RSGS); J. Fertig, V. Companys, R. Guilanya, R. Bauske, A. Accomazzo, S. Liodot, A. Hubault, R. Kay (RMOC);

## Subject: Assessment of prediction error for lander delivery

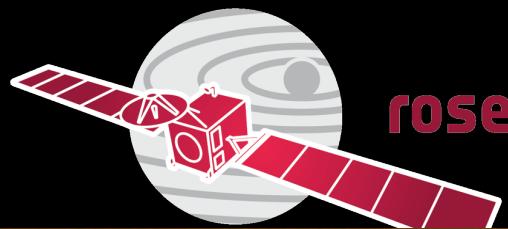
The navigation errors during the delivery sequence for both the orbiter and the lander for both site J (nominal) with strategy O1 and C (backup) with strategy O2 have been assessed as part of the LSSP-2 activity. The main results are specified in the LAFR delivered together with the LSSP-2 operational products. This memo shows results that have been requested by SONC but are not contained in the operational products.

The maximum expected navigation errors right before the pre-delivery manoeuvre for site J with strategy O1 (at a 30x30km orbit) are:

## Comparison between dispersion ellipse for site J

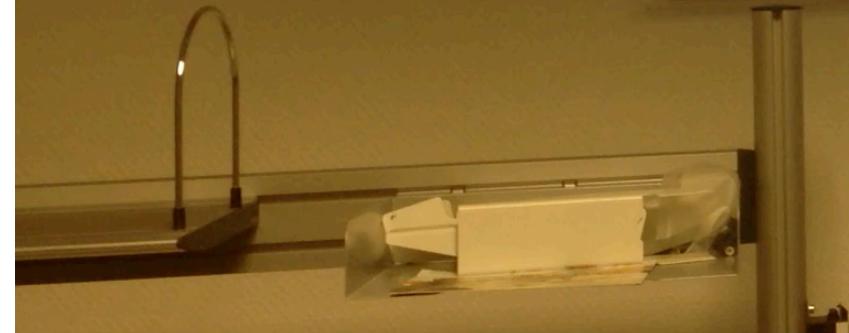
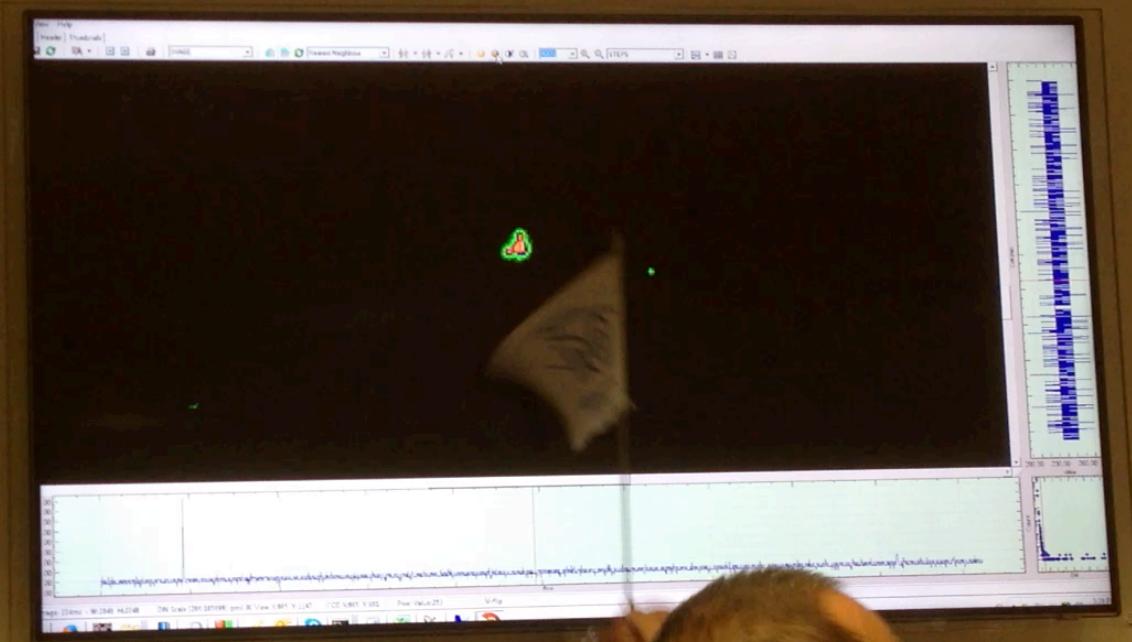


- show  
**LSSP-3\_System\_Report\_L32\_10102014**



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# Philae Landing



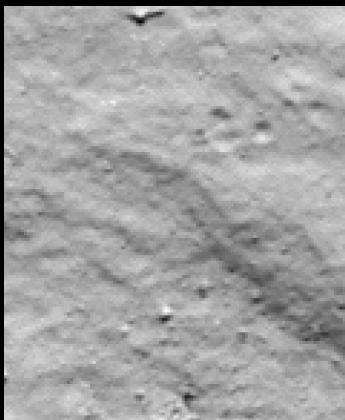
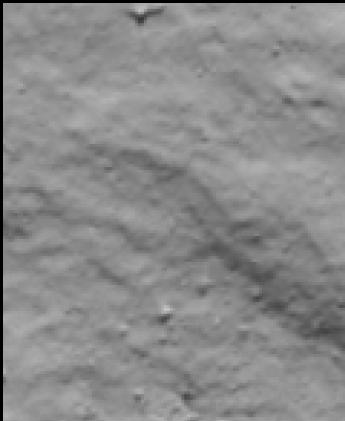


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Philae Landing



before

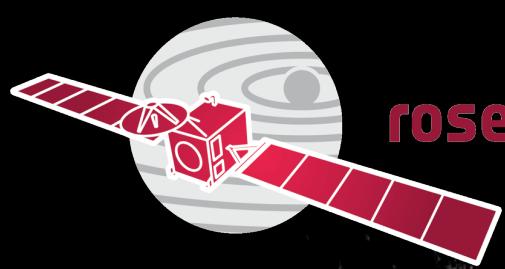


after

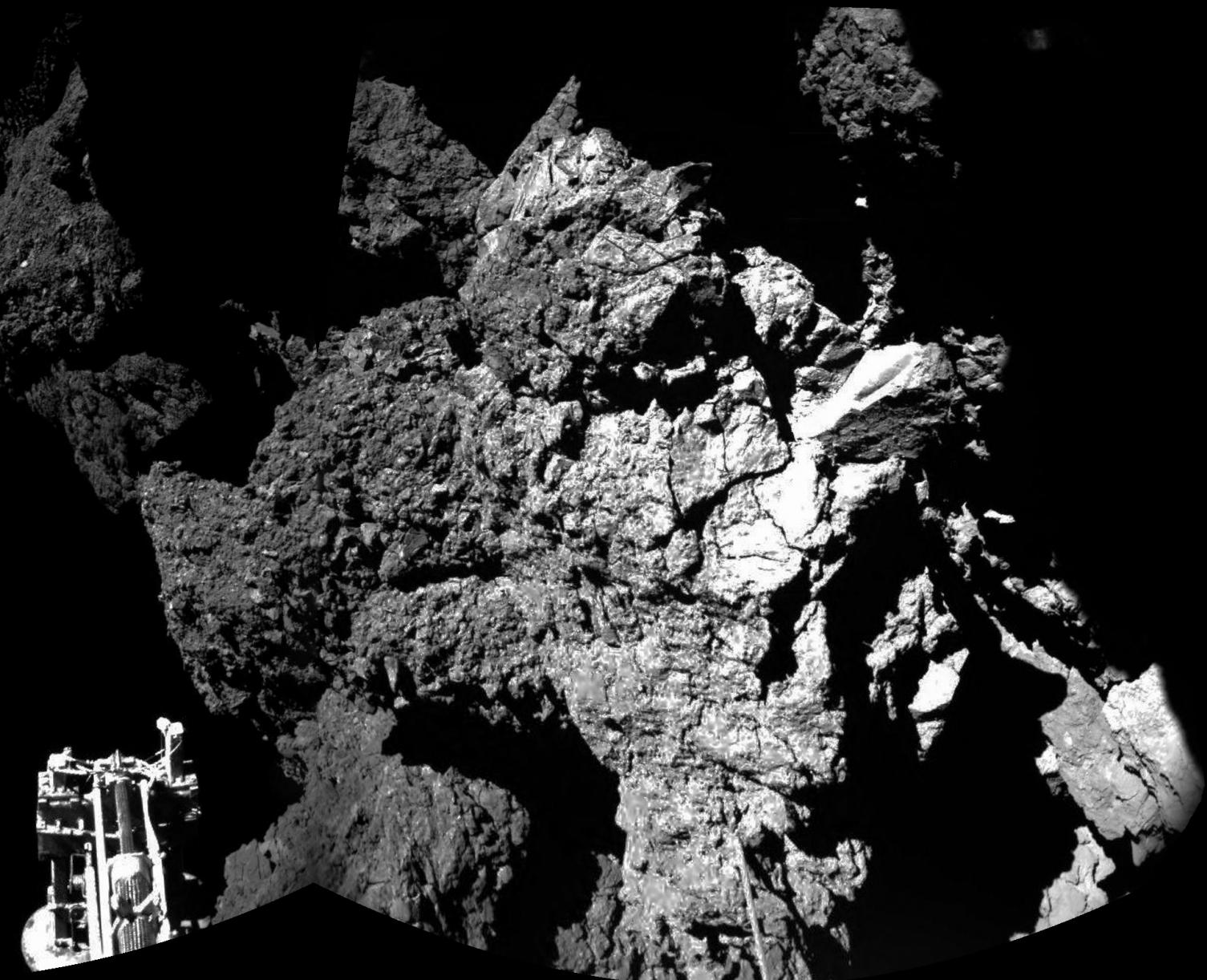


difference

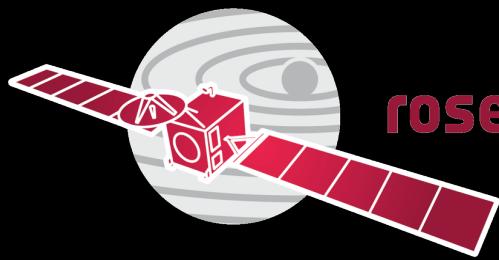




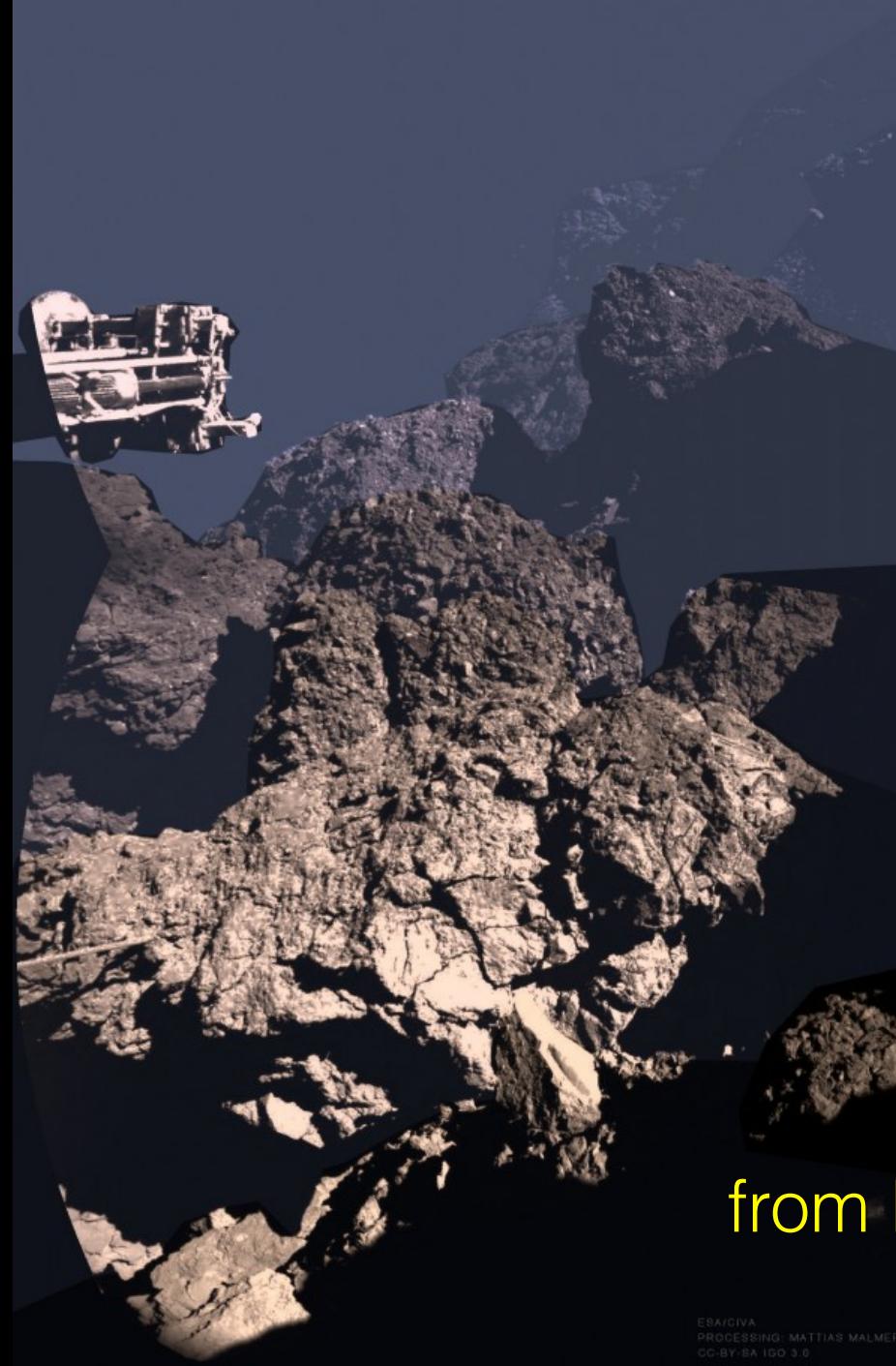
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from M. Malmer

European Space Agency

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